PRODUCT MANUAL



Communications Device

TX325 Satellite Transmitter for GOES V2



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Please read first

About this manual

Please note that this manual was produced by Campbell Scientific Inc. primarily for the North American market. Some spellings, weights and measures may reflect this. In addition, while most of the information in the manual is correct for all countries, certain information is specific to the North American market and so may not be applicable to European users. Differences include the U.S. standard external power supply details where some information (for example the AC transformer input voltage) will not be applicable for British/European use. Please note, however, *that when a power supply adapter is ordered from Campbell Scientific it will be suitable for use in your country*.

Reference to some radio transmitters, digital cell phones and aerials (antennas) may also not be applicable according to your locality. Some brackets, shields and enclosure options, including wiring, are not sold as standard items in the European market; in some cases alternatives are offered.

Recycling information for countries subject to WEEE regulations 2012/19/EU



At the end of this product's life it should not be put in commercial or domestic refuse but sent for recycling. Any batteries contained within the product or used during the products life should be removed from the product and also be sent to an appropriate recycling facility, per The Waste Electrical and Electronic Equipment (WEEE) Regulations 2012/19/EU. Campbell Scientific can advise on the recycling of the equipment and in some cases arrange collection and the correct disposal of it, although charges may apply for some items or territories. For further support, please contact Campbell Scientific, or your local agent.

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1. Introduction

The TX325 transmitter sends data via Geostationary Operational Environmental Satellites (GOES) and is the successor to the TX321. In the Western Hemisphere, the TX325 is compatible for use with NOAA GOES DCS with a coverage range including Canada, the United States of America, and Mexico—as well as most countries in Central America and many South American countries.

The TX325 is the telemetry backbone for many data collection platforms (DCP) that use GOES. The satellite transmitter can be integrated with several Campbell Scientific data loggers and is an available communications option for many systems, serving a wide range of applications.

2. Precautions

- READ AND UNDERSTAND the Safety section at the back of this manual.
- Although the TX325 is rugged, it should be handled as a precision scientific instrument.
- A proper antenna connection is required before transmission occurs. Failure to use a properly matched antenna cable and antenna may cause permanent damage to the radio frequency (RF) amplifiers.
- People using pacemakers or hearing aids should consult a physician first before interacting with the satellite terminal within one meter.
- Do not install the satellite terminal during electrical storms, which could result in severe personal injury or death.
- Never use the satellite terminal where blasting work is in progress. Observe all restrictions and follow any regulations or rules. Areas with a potentially explosive environment are often, but not always, clearly marked.
- Do not stand in front of the antenna. This device emits radio frequency energy. To avoid injury, do not place head or other body parts in front of the satellite outdoor unit (ODU) when system is operational. Maintain a distance of 1 m or more from the front of the satellite terminal ODU.

- Do not disassemble your satellite terminal. The unit does not contain consumer-serviceable components. Changes or modifications to the terminal not expressly approved by Campbell Scientific will void the warranty and could void your authority to operate this equipment.
- Properly connect the protective earth ground to help minimize chance of damage.
- Leaving a computer connected to the unit may result in excessive data usage and overage charges.
- To avoid impaired terminal performance, ensure the unit antenna is not damaged or covered with foreign material such as paint or labeling.
- When connecting the interface cables, do not use excessive force.
- Use only a soft, damp cloth to clean the terminal and antenna.

3. Initial inspection

- Upon receipt of the TX325, inspect the packaging and contents for damage. File damage claims with the shipping company.
- Check the ships with list to ensure all components are received.

4. QuickStart

Use our *Device Configuration Utility* to enter the required National Environmental Satellite Data and Information Service (NESDIS) information that is unique to each data collection platform (DCP). This QuickStart is for the CR6 (\geq OS 10), CR300-series (\geq OS 10), CR1000X (\geq OS 4), and GRANITE-series (\geq OS1) data loggers.

- 1. Connect the data logger **RS-232** to the TX325 **RS-232** connector and connect the data logger to a power supply.
- 2. Connect the TX325 power connector to the transmitter power supply.

CAUTION:

The TX325 should never directly draw power from the data logger. The transmitter draws 2.5 A of power during transmission. The data logger can provide a maximum of

0.9 A over its 12 VDC terminals, which is insufficient. To avoid transmission issues, ensure that the TX325 power is directly connected to the charging regulator or the battery.

- 3. Connect to the data logger using *Device Configuration Utility*.
 - a. Do the following to directly connect your data logger to the *Device Configuration Utility*.
 - i. Use the USB cable to connect the data logger to the computer.
 - ii. Click your data logger model for the **Device Type** in the **Device Configuration** *Utility*.
 - iii. Click Direct for the Connection Type.
 - iv. Select the **Communication port** on the computer to which the data logger is connected.
 - v. Click Connect.
 - b. For data loggers on an IP connection, do the following to remotely connect with the *Device Configuration Utility*:
 - i. Click your data logger model for the **Device Type** in the **Device Configuration Utility**.
 - ii. Click IP for the Connection Type.
 - iii. Type the Server Address.
 - iv. Type the PakBus/TCP Password.
 - v. Click Connect.
- 4. Click the **Settings Editor** tab.

5. Click the GOES Radio sub tab (Figure 4-1 [p. 4]).

Device Type	Deployment Logger Control Data Monitor Data Collection File Control Manage OS VW Diagnostics Settings Editor Terminal
Q Search	
CR6 Series	A Datalognar CS I/O ID DDD Naturyk Sanurar GOES Radio Mis.El ComPorts Sattings Ethernat Advanced TJ S
CR800 Series	bladigge blad a mini herministe meta solar anna bladinge bladinet herdinet herdinet her
CRVW Series	Goes Radio Enabled
GRANITE 10	Enabled V
GRANITE 6	ComPort
GRANITE 9	
Datalogger (Other)	Self-Timed Message Window (seconds)
CR 10X	Bandom Transmission Reneat Count
CR 10X-PB	
CR 10X-TD	Platform ID
CR200 Series	
CR23X	Random Transmission Baud Rate
CR23X-PB	300 BPS ~
CR23X-TD	Random Transmission Channel
CR5000	195
CR510	Self-Timed Baud Rate
CR510-PB	300 BPS 🗸
CR510-TD	Self-Timed Channel
CR9000X	175 🗘
GRANTTE	Random Transmission Interval
TEMP 120	00:01:00
VOLT 100 Series	Self-Timed Transmission Interval
VALUE 205	00:01:00:00
Retwork Berinheral	Self-Timed Transmission Offset
a wetwork Peripheral	00:20:45
NE 100	Current Platform ID
NL200 Series	0105561e
NL240	Current transmitter date/time
NL241	2019-08-19 20:32:06.1
NL300	Radio Operating Sytem Version
D Bowinhowsl	15:22:26 01/17/2018
Connection Type	Current Battery Voltage
Direct IP	13 121

Figure 4-1. Device Configuration Utility GOES Radio screen

- 6. Select Enabled from the Goes Radio Enabled field.
- 7. Select the **Com Port** to which the GOES radio is connected.
- 8. Type the **Self-timed Message Windows (in seconds)** as assigned by the GOES DCS Program.
- 9. Type the Platform ID (in HEX) as assigned by the GOES DCS Program.
- 10. Select the Random Transmission Baud Rate as assigned by the GOES DCS Program.
- 11. Type the Random Transmission Channel as assigned by the GOES DCS Program.
- 12. Select the Self-Time Baud Rate as assigned by the GOES DCS Program.
- 13. Type the Self-Time Channel as assigned by the GOES DCS Program.
- 14. Type the **Random Transmission Interval** as assigned by the GOES DCS Program. Format is hh:mm:ss.
- 15. Type the **Self-timed Transmission Interval** as assigned by the GOES DCS Program. Format is dd:mm:hh:ss.

- 16. Type the **Self-timed Transmission Offset** as assigned by the GOES DCS Program. Format is hh:mm:ss.
- 17. Click the **Deployment** tab.

1

- 18. Click the **Com Port Settings** sub tab.
- 19. Select 9600 for the Baud Rate.

<u>File Backup Options I</u>	<u>H</u> elp Ne	w Version ★				
Device Type		Deployment				
Q Search	\otimes	Datalogger	Com Por	ts Settings	Ethernet	CS I
CR 1000X Series	^	Select the	ComPort:	RS-232		~
CR300 Series CR3000		Ba	aud Rate:	9600 Fixe	d \sim	
CR6 Series		Confi	guration:			\sim
CR800 Series		Beacon	Interval:	0	•	
CRVW Series						
GRANITE 10		Verify	Interval:	0	•	
GRANITE 6						
GRANITE 9						

20. Click Apply to save the changes.

Now the settings are stored in the data logger. CRBasic programming is required to push data over the network. The GOESTable() and GOESField() CRBasic instructions used in conjunction with DataTable() facilitate the transmission of data across the GOES satellite network.

4.1 Data collection platform (DCP) installation

- 1. Yagi antenna installation procedure:
 - a. Mount the Yagi antenna to a pole or mast by using the U-bolts included with the antenna mount.
 - b. Attach elements to boom.

NOTE:

When attaching elements to the boom, make sure to place them such that the number of grooves on the element equals the number of dimples on the boom. For example, the element with four grooves should be placed at the spot on the boom with four dimples, and so forth.

- c. Aim the Yagi antenna at the spacecraft; azimuth and elevation angle positions are included on the bracket label.
- 2. GPS antenna installation procedure:
 - a. Connect the GPS cable to the GPS antenna.
 - b. Route the cable through the 0.75-inch IPS threaded pipe and insert the pipe into the GPS antenna.



c. Mount the 0.75-inch IPS threaded pipe to a crossarm by using the Nu-Rail® fitting or right-angle mounting kit.



CAUTION:

The GPS antenna will not receive a GPS signal through steel roofs or steel walls. Concrete might also be a problem. Heavy foliage, snow, and ice will attenuate the GPS signal.

- 3. Mount the TX325, the power supply, and the data logger to the backplate of an enclosure.
- 4. Mount the enclosure and solar panel to the pole or tripod.
- 5. Connect the COAXNTN cable to the Yagi antenna. Route the COAXNTN cable through the enclosure conduit and connect it to the **RF Out** connector on the TX325 (Figure 4-2 [p. 7]).



Figure 4-2. TX325 connectors

- 6. Route the GPS antenna cable through the enclosure conduit and connect it to the **GPS** connector on the TX325 (Figure 4-2 [p. 7]).
- 7. Plug the green connector from the power supply to the green receptacle on the TX325.

CAUTION:

The TX325 should never directly draw power from the data logger. The transmitter draws 2.5 A of power during transmission. The data logger can provide a maximum of 0.9 A over its 12 VDC terminals, which is insufficient. To avoid transmission issues, ensure that the TX325 power is directly connected to the charging regulator or the battery.

8. Connect the data logger to the TX325 RS-232 terminal.

9. Route the solar panel cable through the enclosure conduit and connect the red and black wires to the CHG terminals on the CH150, CH200, or CH201.

5. Overview

The TX325 can transmit either self-timed or random GOES messages to the GOES West and GOES East satellites. In a typical configuration, the TX325 is connected to a data logger via an RS-232 serial connection. The data logger makes measurements, then formats those values to create a data packet, which is transferred to the transmitter at time of transmission. The data logger buffers the message until its transmission window (or random transmission time), then transmits the data at either 300 or 1200 bps.

GPS is required for the radio to work in the GOES network. The GOES network is a TDMA network that requires all the radios in the network to have exact timing of their transmissions so they don't step on each other during transmissions. Extremely accurate timing is obtained from the integrated GPS receiver (\pm 100 µs), and the internal clock is capable of maintaining accurate time for a minimum of six days without a GPS fix. If the TX325 finds itself without an accurate time, it suspends data transmissions until an accurate time is obtained. The GPS time is synced every 11 hours. The data logger clock is synced with the GPS time of the TX325 when using a GRANITE-series, CR6, CR1000X-series, and CR300-series data logger.

NOTE:

If the user does not want the data logger synced to the GPS time, they can adjust the UTCOffset setting using the SetSetting() CRBasic instruction in the data logger program or using the *Device Configuration Utility* software (Settings Editor > Advanced > UTC Offset). See Table 7-4 (p. 19) for more information.

Features:

- NESDIS HDR V2 certified
- Based on Signal Engineering OmniSat3 design
- Compatible with GOES DCS system
- Easy integration with Campbell Scientific data loggers
- Field tested and proven track record of reliability
- Embedded GPS receiver for stabilized internal time keeping and transmit frequency for long service intervals
- Low standby current consumption for battery-powered systems at remote DCP installation sites
- Quick assessment of radio health via monitoring of diagnostic data from the radio

• Compatible CRBasic data loggers: GRANITE series, CR6, CR1000X, and CR300 series are fully compatible. The CR3000, CR800 series, and CR1000 have limited compatibility.

5.1 GOES, NESDIS, and transmit windows

GOES coverage area is latitude 68° North to 68° South and longitude 150° East to 2° West (see Figure 5-1 [p. 9]). GOES satellites have orbits that coincide with the Earth rotation, allowing each satellite to remain above a specific region (geosynchronous). GOES has two satellites: GOES East located at 75° West longitude and GOES West located at 135° West longitude. Both satellites are located over the equator. Within the United States, odd-numbered channels are assigned to GOES East, and even-numbered channels are assigned to GOES West. Channels used outside of the United States are assigned to either spacecraft.



Figure 5-1. Coverage of GOES East and GOES West satellites

The GOES system is administered by the National Environmental Satellite Data Information Service (NESDIS), which assigns addresses, uplink channels, and self-timed/random transmit time windows. Self-timed windows allow data transmission only during a predetermined time frame (typically 10 seconds every hour). Random windows are for applications of a critical nature, such as flood reporting, and allow transmission immediately after a threshold has been exceeded. The transmission is randomly repeated to ensure it is received. A combination of self-timed and random transmission can be executed by the TX325.

Refer to Eligibility and getting onto the GOES system (p. 42) for more information.

6. Specifications

Compliance:	Refer to Compliance documents and certificates (p. 80) and www.campbellsci.com/tx325 \Box
Transmissions supported:	Timed (scheduled), random
Data formats:	ASCII (SHEF), pseudo binary
Radio module:	OmniSat-3
Temperature range	
Operating:	–40 to 60 °C
Storage:	–55 to 75 °C
Case dimensions	
Without connectors:	15.88 x 12.7 x 4.57 cm (6.25 x 5 x 1.8 in)
With connectors:	15.88 x 14.99 x 4.57 cm (6.25 x 5.9 x 1.8 in) additional clearance required for cables, wires, and antennas
Weight:	0.77 kg (1.7 lb)
Supply voltage range:	10.5 to 16 VDC
Current drain at 12 VDC	
While transmitting:	< 2.5 A (1.8 typical)
Standby:	< 5 mA (2.8 typical)
During GPS acquisition:	< 50 mA (25 mA typical)
Baud rates:	300 and 1200 bps

Transmit power	
Maximum:	31 dBm (300 bps), 37 dBm (1200 bps)
Max EIRP ¹ :	41 dBm (300 bps), 47 dBm (1200 bps); based on a 11 dbm gain antenna with 1 dbm line loss
Typical EIRP ¹ :	37 to 41 dBm (300 bps), 43 to 47 dBm (1200 bps)
Frequency range:	401.701 to 402.09925 MHz
Initial frequency stability:	± 20 Hz disciplined to GPS (GPS fix occurs after power up and once per day thereafter)
Channel bandwidth:	1500 Hz (300 bps), 2250 Hz (1200 bps)

GPS receiver

NOTE:
The TX325 can source up to 19 mA at 2.7 V for an external GPS antenna. Campbell
Scientific recommends a maximum antenna Low-Noise Amplifier (LNA) of 1.5 dB.

Maximum RF input gain:	3.3 V active
Receiver type:	25 dB
Timekeeping	
Initial accuracy:	$\pm 100 \ \mu s$ (synchronized to GPS)
Drift:	±40 ms/day (without GPS)
GPS schedule:	1 fix at power up (updated at ~11-hour rate)
Transmission continuation without GPS fix:	6 days
Interface connectors	
RS-232:	DB9 F, DCE, 3-wire RS-232
Satellite RF transmit out:	Type N jack
GPS:	SMA jack
Power:	2-pin screw terminal, 0.2 in. pitch

¹Equivalent, isotropically radiated power (EIRP)

7. Installation

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7.1 Field site requirements

Prepare an area for the station, approximately five meters in diameter. Remove any obstructions, brush and tall weeds, while disturbing the ground surface and other natural vegetation as little as possible.

The GPS antenna must have a clear view of most of the sky and the transmission antenna must have a clear view of the spacecraft. The TX325 must be installed in a well-desiccated, environmentally sealed enclosure. Its mounting plate has keyholes for securing the TX325 to the backplate of a Campbell Scientific enclosure. Most GOES systems are powered by a battery charged by a solar panel. The solar panel must have a clear view of the southern sky. Pay special attention to winter sun angles.

7.2 LED function

A green **Status** LED and a red **Failsafe** LED indicate the state of the TX325 transmitter by using various blink patterns. Table 7-1 (p. 13) and Table 7-2 (p. 13) provide the blink patterns for the green **Status** and red **Failsafe** LEDs, respectively.

Table 7-1: Green LED Status indicator blink patterns			
Blink pattern	Indicates		
	Normal software is running.		
At power up, blinks on and off two times.	RS-232 control interfaces enabled.		
	Power-up initialization complete and ready to receive commands.		
At power up, blinks on and off	Bootloader software is running.		
three times.	Ready to load new operating system.		
On continuously.	Transmitter failed to start up normally after power up. Turn the transmitter off and on to reboot.		

Table 7-2: Red LED Failsafe indicator blink patterns			
Blink pattern	Indicates		
Blinks on and off four times per second.	A transmission is in progress.		
Blinks on and off two times per second for 30 s.	The post-transmit interval is in progress. The transmitter enters this state after its RF output is turned off either by a Reset command or by the normal completion of a data message transmission. The radio needs to wait 30 seconds before making another transmission to keep it from going into Failsafe mode.		
On continuously.	TX325 is in the Failsafe mode. To clear a Failsafe mode, push the Reset button (Figure 8-1 [p. 33]). A power cycle will NOT clear the Failsafe mode.		

7.3 Ports and connectors

The RS-232 port is a DB9 male connector configured as DTE. Only three pins are used, transmit on pin two, receive on pin three, and ground on pin five. Transmit is an output and receive is an input to the TX325. The RS-232 port allows the transmitter to be connected to a data logger. Refer to the following table for the cable options and data logger connection.

Table 7-3: Cable options, data logger compatibility, and data logger connections				
Cable description	Compatible data loggers	Data logger connection		
RJ45 to DB9 female cable (-R option when ordered with the TX325)	Granite-series, CR6, CR1000X	RS-232/CPI RJ45 port		
SC110 TX/RX cable (-C option when ordered with the TX325)	Granite-series, CR6, CR1000X	White: Odd C or U terminal Brown: Even C or U terminal Yellow: G Clear: G or ↓		
RS-232 DB9 female to DB9 male serial cable (-S option when ordered with the TX325)	CR800-series, CR300-series, CR3000, CR1000	RS-232 9-pin port		
Female null modem serial cable > SC105 interface ¹ > SC12 CS I/O cable (-IO option)	Granite-series, CR6, CR1000X	CS I/O port		
¹ For the SC105, use the default CS I/O ME Baud Rate and Baud Rate settings of 9600.				

The **RF Out** connector is for attaching the transmission antenna. A properly matched antenna cable and antenna must be connected to the TX325 before transmission occurs.

WARNING:

Failure to use a properly matched antenna cable and antenna may cause permanent damage to the radio frequency (RF) amplifiers.

The nominal impedance is 50 ohms; the frequency range is approximately 400 to 403 MHz. Maximum EIRP for GOESV2 is 41 dBm for 300 bps and 47 dBm for 1200 bps. The antenna gain can be set while configuring the transmitter. If not set, the TX325 will use an antenna gain of 11 dBi and a transmitter-antenna cable loss of 1 dB. Under those conditions, at 300 bps transmission rates, the maximum transmit power from the transmitter is 31 dBm. At 1200 bps, the transmit power is 37 dBm.

Effective Antenna Gain is defined as antenna gain (in dBi) minus the transmitter-antenna cable loss (in dB). If the **Effective Antenna Gain** is set and enabled, the transmitter automatically adjusts the radio power output to limit the EIRP to the maximum allowed value. The adjusted power output may be up to 37 dBm, depending on the **Antenna Gain** and **Baud Rate** settings.

The **GPS** port on the TX325 is an SMA female connector for attaching an active 3.3 V GPS antenna. Operation without a GPS antenna connected will not cause damage, but the transmitter will not transmit without a valid GPS fix. The transmitter uses the GPS receiver for two functions.

The precise GPS time is used to ensure scheduled transmissions occur at the proper time. The one-second GPS synchronization pulse is used to ensure a precise, drift-free carrier frequency.

The TX325 power connector has two pins: ground and 12 V for connection of the power supply. The input power requirement is 10.5 to 16 VDC can use up to 2.5 A. A power supply consisting of a CH150, CH200, or CH201 regulator, BP12 or BP24 battery, and a solar panel typically can support these requirements. The regulator connects to the TX325 power connector.

CAUTION:

The TX325 should never directly draw power from the data logger. The transmitter draws 2.5 A of power during transmission. The data logger can provide a maximum of 0.9 A over its 12 VDC terminals, which is insufficient. To avoid transmission issues, ensure that the TX325 power is directly connected to the charging regulator or the battery.

7.4 Transmission antenna

CAUTION:

Do not stand in front of the antenna. This device emits radio frequency energy. To avoid injury, do not place head or other body parts in front of the satellite outdoor unit (ODU) when system is operational. Maintain a distance of 1 m or more from the front of the satellite terminal ODU.

The TX325 transmission antenna is a right-hand circular polarized Yagi with 11 dBi gain. A bracket is included with the antenna for mounting to a mast or pole. The antenna is directional and should be aimed at the spacecraft. Both elevation and azimuth are unique to the location on the planet and must be set. A poorly aimed antenna will cause a drop in signal strength or possibly prevent successful transmission. As a guide, if the antenna is aimed 20 degrees off the spacecraft, the received power will be half of a properly aimed antenna. Beyond 20 degrees, the received power drops off quickly.

NOTE:

When attaching elements to the boom, make sure to place them such that the number of grooves on the element equals the number of dimples on the boom. For example, the element with four grooves should be placed at the spot on the boom with four dimples, and so forth.

The *Device Configuration Utility* software has a tool for helping to point the transmitter antenna.

 When connected to the CR6, CR1000X, CR350, or CR300 Series data logger, click the Deployment > GOES tab. 2. Under the General Radio Status, scroll down to the Orient Antenna link.

Securitys Editor			
alogger Com Ports Settings Ethernet CS I/O IP PPP GOES Network	Services TLS Advanced		
Several Radio Options COES Enabled GOES CMPart: R5-232 GOES Platform ID: 12245678 OES Antenna Gain 0 GOES Time: 1202-09-3-31 20:20:00.7 Self Timed TX Options Channel: 197 0 BALD Rate: 1200 BPS - GOES TX Rate: 0 0 1:1 0:0 0 0 0		Random TX Options Channel: 195 © BAUD Rate: 300 BPS - GOES TX Rate: 0 © 1 50 © 50 ©	
X Offset Time: 0 : 20 0 : 0 : TX Window: 10 0		Repeat Count:	
General Radio Status			
OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe has not be Radio Temperature: 20 °C Current Battery: 13.494 V	en tripped.		
OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe has not be Radio Temperature: 20 °C Current Battery: 13.494 V Last Transmission Status	en tripped.		
OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe has not be Radio Temperature: 20 °C Current Battery: 13.494 V Last Transmission Status Status:	en tripped. GPS Status Antenna Stat	us; Antenna is OK.	
OS Version: 10:25:03 04/23/2020 Faik-safe Status: Radio 1s 0 K. Failsafe has not be Radio Temperature: 20 °C Current Battery: 13.494 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V	en tripped. GPS Status Antenna Stat Acquisition Stat	us: Antenna is OK. us: The GOES radio has a valid GPS fix.	
OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio 1s 0K. Failsafe has not be Radio Temperature: 20 °C Current Battery: 13.494 V Last Transmission Status Status: Battery Volts Bufore TX: 13.414 V Battery Volts Buforg TX: 13.242 V	GPS Status Antenna Stat Acquisition Stat Last Fix Tir	us: Antenna is OK. us: The GOES radio has a valid GPS fix. ne: 2022-03-31 09:23:27	
OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is 0 Kr. Failsafe has not be Radio Temperature: 20 ° C Current Battery: 13.494 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V Battery Volts During TX: 13.242 V Duration: 1740 maec	en tripped. GPS Status Antenna Stat Last Fix Tir Number of Missed Fix	us: Antenna is OK. us: The GOES radio has a valid GPS fix. ne: 2022-03-31 09:23:27 es: 0	
OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is 0K. Failsafe has not be Radio Temperature: 20 °C Current Battery: 13.494 V Last Transmission Status Battery Volts Before TX: 13.414 V Battery Volts During TX: 13.242 V Duration: 1740 msec Forward Power: 0.75 W	en tripped. GPS Status Antenna Stat Acquisition Stat Last Fix Tr Number of Missed Fix Locat	us: Antenna is OK. us: The GOES radio has a valid GPS fix. ne: 2022-03-31 09:23:27 es: 0 on Lat 41.76335, Long -111.85755, Alt 901.6 m	

3. Click Orient Antenna. A small Orient Antenna window will open. Select the satellite (GOES-16 [East] or GOES-16 [West]).

NOTE:

GOES has two satellites, GOES East and GOES West (Figure 5-1 [p. 9]). Both satellites are located over the equator. Within the United States, odd-numbered channels are assigned to GOES East, and even-numbered channels are assigned to GOES West. Channels used outside of the United States are assigned to either spacecraft. If you are unsure check with DCS Help Desk online at https://dcs1.noaa.gov

Check that the **Latitude**, **Longtitude**, **Elevation**, and **Magnetic Declination** are correct for your site; this information should be pulled from the GPS receiver. The bottom window will display the correct Azimuth and Elevation for pointing your antenna.

Transmitter Latitude: 41.76335 Transmitter Longitude: -111.85755 cansmitter Elevation (m): 901.6 Magnetic Declination: 11.42 Elevation angle of the antenna on the horizontal plane. Elevation: Elevation: 29.2° Tilt angle of the antenna from the horizontal plane.	Transmitter Latitude: 41.76335 Transmitter Longitude: -111.85755 ransmitter Elevation (m): 901.6 Magnetic Declination: 11.42 East Azimuth: 143.2° Rotation angle of the antenna on the horizontal plane. Elevation: 29.2° Tit angle of the antenna from the horizon.	Align to	o Satellite	GOES-16 (East)	~	1	
Transmitter Longitude: -111.85755 ransmitter Elevation (m): 901.6 Magnetic Declination: 11.42 East Castor of the antenna on the horizontal plane. Elevation: 29.2° Tilt angle of the antenna from the horizon	Transmitter Longitude: 111.85755 ansmitter Elevation (m): 901.6 Magnetic Declination: 11.42 East Contain angle of the antenna on the horizontal plane. Elevation: 29.2° Tilt angle of the antenna from the horizon.	Transmitter	r Latitude	41.76335			
Ansmitter Elevation (m): 901.6 Magnetic Declination: 11.42 East Azimuth: 143.2° Elevation: 29.2° Tilt angle of the antenna plane. Tilt angle of the antenna prom the horizon	Ansmitter Elevation (m): 901.6 Magnetic Declination: 11.42 East Azimuth: 143.2° plane. Elevation: 29.2° Tilt angle of the antenna from the horizon.	Transmitter l	Longitude	-111.85755			
Magnetic Declination: 11.42 East Azimuth: 143.2° Rotation angle of the antenna on the horizontal plane. Elevation: 29.2° Tilt angle of the antenna	Magnetic Declination: 11.42 East Azimuth: 143.2° Rotation angle of the antenna on the horizontal plane. Elevation: 29.2° Tilt angle of the antenna from the horizon.	ransmitter Elev	vation (m)	901.6			
Rotation angle of the Azimuth: 143.2° antenna on the horizontal plane. Elevation: 29.2° Tilt angle of the antenna	Azimuth: 143.2° Rotation angle of the antenna on the horizontal plane. Elevation: 29.2° Tilt angle of the antenna from the horizon.	Magnetic D	eclination	11.42		East	~
	nom the honzon.	Elevation:	29.2°	plane. Tilt angle of the ar	ntenr	na	

TIP:

To use this tool with the CR3000, CR1000, or CR800-series, select a newer data logger, such as the CR1000X, and use the offline mode (File> Offline Mode>CR1000X Measurement and Control Datalogger with a TX325/TX326 Radio). In the Offline Mode, click the Deployment > GOES tab then click Orient Antenna to access the Orient Antenna window. Values for Latitude, Longitude, Elevation, and Magnetic Declination need to be manually entered.

7.5 GPS antenna

The GPS antenna mounts to the end of a crossarm by using a 0.75-inch IPS threaded pipe and a 0.75-inch-by-1-inch Nu-Rail® fitting or right-angle mounting kit. Mount the GPS antenna above obstructions, but with the shortest cable possible. The GPS antenna will not receive GPS signals through steel roofs, steel walls, or possibly concrete. Heavy foliage, snow, and ice will attenuate the GPS signal. An unobstructed view provides better GPS performance resulting in fewer (or no) missed transmissions. Poor GPS antenna placement increases the number of missed transmissions, and possibly stops all GPS transmissions.

7.6 Data logger programming

NOTE:

This section provides programming information for the GRANITE-series (\geq OS 1), CR6 (\geq OS 10), CR1000X (\geq OS 4), and CR300-series (\geq OS 10), data loggers. For information on programming the CR3000, CR800-series, and CR1000 data loggers, refer to TX321 program converted to TX325 program (CR1000, CR3000, CR800-series) (p. 69) and the example program at www.campbellsci.com/downloads/tx325-example-program-cr3000-cr1000-cr800 \Box or contact Campbell Scientific.

The CRBasic program can read and enter TX325 settings. Settings can also be entered using the *Device Configuration Utility* (see QuickStart [p. 2]). Table 7-4 (p. 19) provides the TX325 settings that can be read and entered. Table 7-5 (p. 22) provides the read-only settings.

The CRBasic program should include the GOESTable() and GOESField() instructions used in conjunction with the DataTable() instruction to facilitate the transmission of data across the GOES satellite network. The GOESTable() instruction has the following syntax:

GOESTable (Result, ComPort, Model, BufferControl, Fields_Scan_Order,Newest_ First,Format)

The **Result** is a string variable that holds either the data to be output in its specified format or a message indicating there are no data to output to the transmitter. For the **Model**, enter 3 to use the TX325. For the **BufferControl**, a value of 0 writes to the self-timed buffer and a value of 1 writes to the random buffer. Data formats and transmission durations (p. 43) discusses the **Format** options.

The GOESField() instruction has the following syntax: GOESField(NumVals, Decimation, Precision, Width, SHEF)

The NumVals is the number of historical values of the field to output. For **Decimation**, enter 1 to output every value, enter 2 to output every other value, etc. Width specifies the number of characters in the field. Use empty quotes ("") for SHEF¹ if no SHEF code is specified.

¹Standard Hydrologic Exchange Format (SHEF) is a text based format developed by the National Weather Service (NWS) for exchange of real time operational data with other agencies.

An example of using the the GOESTable() and GOESField() instructions follows:

```
DataTable (ST_DATA, TRUE, -1)
DataInterval(0, 15, Min, 4)
GOESTable (st_table_results, COMRS232, 3, 0, TRUE, TRUE, 3)
GOESField (4, 1, 3, 6, "")
Sample (1, battery_voltage, IEEE4)
GOESField (4, 1, 3, 6, "")
Sample (1, panel_temperature, IEEE4)
EndTable
```

In the main portion of the program, settings are written using **SetSetting()** instruction with the following the syntax:

```
SetSetting ( "FieldName", Value )
```

The FieldName must be enclosed in quotes as shown. The following example instruction sets the port used to communicate with the TX325 to the RS-232 port:

```
SetSetting("GOESComPort", COMRS232)
```

The CRBasic program reads the TX325 settings using the following format:

```
Variable = Settings.FieldName
```

For example, goes_comport = Settings.GOESComPort reads the Com port setting and stores it in the GOESComPort variable. The TX325 settings are typically read in a SlowSequence section of the program. Table 7-4 (p. 19) provides the TX325 settings that can be set and read. Table 7-5 (p. 22) provides the read-only settings.

A downloadable example program is available at: www.campbellsci.com/downloads/tx325example-program-granite-cr6-cr1000x-cr300 \square .

7.6.1 Read and write settings

Table 7-4: Read and wri	te TX325 settings	
Field name	Device Configuration Utility setting	Description
GOESComPort	GOES COM Port	Port used to communicate with the GOES transmitter.
GOESEnabled	GOES Enabled	Controls whether the data loggers polls the GOESComPort to see if a TX325 radio is attached to it. With the default setting of 0 (not enabled), the data logger ignores all other GOES settings. A value of 1 enables the setting.

Table 7-4: Read and wri	te TX325 settings	
Field name	Device Configuration Utility setting	Description
GOESGainSetting	GOES Antenna Gain	Specifies the maximum specified gain (in dbi) for the antenna minus the loss in the cable connecting the TX325 to the antenna. The maximum value is 14 dBi for 300 bps transmissions and 20 dBi for 1200 bps transmissions. The default value of 0 assumes the antenna has the same effective gain as the Yagi antenna used for certification.
		The TX325 sets the output power so that the EIRP is close to, without exceeding, the maximum EIRP. Maximum permitted EIRP for GOES V2 is 41 dBm for 300 bps and 47 dBm for 1200 bps transmissions.
GOESMsgWindow	Self Timed TX Options> TX Window	Length, in seconds, of the assigned self-timed transmission window assigned by NESDIS. Valid entries are 1 to 110 s.
GOESPlatformID	GOES Platform ID	8-digit hexadecimal identification number assigned by NESDIS. Value is a string.
GOESRTBaudRate	Random TX Options> BAUD Rate	Baud rate for the random transmissions. Valid settings are 100, 300, or 1200. The baud rate must match the user's NESDIS-channel assignment.
GOESRTChanne1	Random TX Options> Channel	Channel used for the random transmission assigned by NESDIS. Valid channel numbers are 0 through 566. The default value of 0 disables random transmissions.

able 7-4: Read and write TX325 settings		
Field name	Device Configuration Utility setting	Description
GOESRTInterval	Random TX Options> TX Rate	Average time between random transmissions. The value is a string entered in the format of Hours:Minutes:Seconds. Typically, the assigned interval is in hours, so the minutes and seconds parameters are left at 0. For example, "01:00:00" setups up an hourly interval. Maximum interval is 24 hours; minimum interval is 1 minute.
GOESSTBaudRate	Self Timed TX Options> BAUD Rate	Baud rate for self-timed transmissions. Valid settings are 300 or 1200. The baud rate must match the user's NESDIS-channel assignment.
GOESSTChanne1	Self Timed TX Options> Channel	Channel used for the self-timed transmission assigned by NESDIS. Valid channel numbers are 0 through 566. The default value of 0 disables the self-timed transmissions.
GOESSTInterval	Self Timed TX Options> TX Rate	Time between self-timed transmissions. The value is a string entered in the format of Days:Hours:Minutes:Seconds. Typically, the assigned interval is in hours, so the days, minutes and seconds parameters are left at 0. For example, "00:01:00:00" sets up an hourly interval. Maximum interval is 14 days; minimum interval is 1 minute.
GOESSTOffset	Self Timed TX Options> TX Offset Time	Time after midnight for the first self-timed transmission as assigned by NESDIS. The value is a string entered in the format of "Hours:Minutes:Seconds". Typically, only hours and minutes are used, and seconds are 0, unless the transmission window is less than 60 seconds. Maximum offset is 23:59:59. A value 0 results in no offset.

Table 7-4: Read and write TX325 settings		
Field name	Device Configuration Utility setting	Description
GOESRepeatCount	Random TX Options> Repeat Count	Number of times within the random transmit interval that the TX325 will transmit the message data. Valid entries are 1 to 3.
UTCOffset		Adjust this setting if you do not want the data logger to use the Coordinated Universal Time (UTC), which is used by the GPS antenna. The data logger automatically syncs to the GPS time. Specify the offset in seconds.

7.6.2 Read-only settings

Table 7-5: Read-only TX325 settings	S	
FieldName	Description	
GOESid	Current ID programmed into the radio. The ID isn't programmed into the radio until right before a radio transmission starts.	
GOESdateTime	Current date and time (UTC) of the TX325 radio. Value is a string.	
GOESversion	Current radio firmware version. Value is a string.	
GOESCurrentbattery	Battery voltage in VDC.	
GOESCurrenttemperature	Current radio temperature in degrees Celsius.	
GOESbatteryBeforeTx	Battery voltage of the radio just prior to its last transmission.	
GOEStemperatureBeforeTx	Radio temperature before the last transmission.	
GOESbatteryDuringTx	Radio-battery voltage during the last transmission.	
GOESLatitude	Latitude in decimal format of the GOES radio.	
GOESLongitude	Longitude in decimal format of the GOES radio.	
GOESAltitude	Altitude of the GOES radio in meters.	

Table 7-5: Read-only TX325 setting	S
FieldName	Description
GOESTimeLastGPSPosition	Date and time (UTC) of the last GPS position fix. Value is a string.
GOESNumberOfMissedGPS	Number of times the radio has failed to get a GPS fix.
GOESTimeLastMissedGPSFix	Last date and time (UTC) that the radio failed to get a GPS fix. Value is a string.
GOESGPSAcquisitionStatus	Acquisition status of the radio GPS. 0 = valid GPS fix 1 = no GPS position fix, no GPS satellites in view 8 = no GPS position fix, no usable GPS satellites in view 9 = no GPS position fix, one usable GPS satellite in view 10 = no GPS position fix, two usable GPS satellites in view 11 = no GPS position fix, three usable GPS satellites in view
GOESGPSAntennaStatus	Status of the GPS antenna. 0 = GPS antenna is working 16 = GPS antenna is not connected 48 = GPS antenna is shorted
GOESFailSafeIndicator	Radio failsafe status. 1 = Failsafe has been tripped 0 = Radio is OK and Failsafe has not been tripped
GOESDurationOfTransmit	Duration of the last transmission of the GOES radio in milliseconds.
GOESForwardTxPower	Forward RF power of the transmitter in watts.
GOESReflectedRfPower	Reflected RF power of the transmitter in watts.
GOESVSWR	Voltage standing wave ratio (SWR) of the radio.
GOESLastTxControlFlags	Control flags used in the last transmission.
GOESLastTxStartTime	Start time (UTC) of the last radio transmission. Value is a string.
GOESLastTxChannel	Channel number used during the last radio transmission.
GOESLastTypeCode	Type of transmission used during the last radio transmission.
GOESLastDatelength	Number of bytes in the last radio transmission.

Table 7-5: Read-only TX325 setting	S
FieldName	Description
GOESLastHDRFlagWord	HDR flag word used in the last radio transmission.
GOESTxResultCode	Status of the last radio transmission. 0 = Last transmission was OK 1 = Transmission aborted, radio battery voltage is too low 2 = Transmission aborted, radio PLL lock failure 3 = Transmission aborted, radio flash is corrupt
GOESCurrentTxState	Current state of the radio. 0 = Idle 1 = Transmission is in progress 2 = Post transmission failsafe wait is in progress

8. Troubleshooting

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For assistance with the TX325, contact Campbell Scientific. Refer to the last page of this document for contact information.

8.1 Check TX325 and data logger power

Do the following to verify the data logger is properly powered:

- 1. Access the *Device Configuration Utility* software.
- 2. Select your data logger for the Device Type and connect the data logger to the computer.
- Click the data logger Data Monitor tab and check the battery voltage in the Status table. Voltage is typically a little over 12 VDC. For example, a reading of 13.5 VDC is acceptable. Lower values such as 11 or 10.5 VDC can keep your system from communicating optimally and may prevent communications.

CAUTION:

The TX325 should never directly draw power from the data logger. The transmitter draws 2.5 A of power during transmission. The data logger can provide a maximum of 0.9 A over its 12 VDC terminals, which is insufficient. To avoid transmission issues, ensure that the TX325 power is directly connected to the charging regulator or the battery.

Do the following to ensure that the TX325 properly powered:

- 1. Ensure that the power connector attached to the TX325 has the correct polarity. To do this, use a multimeter to verify that positive is connected to the positive terminal and negative is connected to the negative terminal.
- 2. Connect the data logger to the TX325.
- 3. Access the *Device Configuration Utility* software.
- 4. Select your data logger for the **Device Type** and connect the data logger to the computer.

5. Click the data logger **Deployment** > **GOES** tab and check the **Current Battery** voltage in the diagnostics at the bottom of the screen and ensure that it is 12 VDC or higher. If the TX325 and data logger are drawing power from the same source, always ensure that the voltage is more than 12 VDC.

logger control is setungs curenier co t/o IP PPP de	OCS Network Services TLS Advanced	
eneral Radio Options		
GOES Enabled		
GOES COM Port: RS-232 V		
GOES Platform ID: 12345678		
DES Antenna Gain 0		
GOES Time: 2022-03-31 20:30:17.8		
elf Timed TX Options	Random TX Options	
Channel: 195	Channel: 195	
BAUD Rate: 300 BPS - GOES V	BAUD Rate: 300 BPS - GOES V	
Coffset Time: 0 🔹 : 0 🔹 : 0 🔹	Repeat Count: 2	
TX Window: 10		
General Radio Status		
OS Version: 10:25:03 04/23/2020		
Fail-safe Status: Radio is OK. Failsafe h	has not been tripped.	
Padia Temperatura: 20 °C		
Badio remperature: 20 °C		
Current Batteny: 13, 464 V		
Current Battery: 13.464 V		
Current Battery: 13.464 V	GPS Status	
Current Battery: 13,464 V Last Transmission Status Status:	GPS Status Antenna Status: Antenna is OK.	
Current Battery: 13,464 V Last Transmission Status Status: Battery Volts Before TX: 13,414 V	GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GPS fix.	
Current Battery: 13.464 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V Battery Volts During TX: 13.242 V	GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GPS fix. Last Fix Time: 2022-03-31 09:23:27	
Current Battery: 13.464 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V Battery Volts During TX: 13.242 V Duration: 1740 msec	GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GPS fix. Last Fix Time: 2022-03-31 09:23:27 Number of Missed Fixes: 0	
Current Battery: 13.464 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V Battery Volts During TX: 13.242 V Duration: 1740 msec Forward Power: 0.75 W	GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GPS fix. Last Fix Time: 2022-03-31 09:23:27 Number of Missed Fixes: 0 Location: Lat 41.76335, Long -111.85755, Alt 901.6 m	

8.2 Check RS-232 connection

Verify the RS-232 cable is connected to both the data logger RS-232 port and the TX325. Check the cable for corrosion, frayed wires, and good contact with the ports on the two devices. RS-232 cables occasionally wear out without visible signs of failure. Keep a spare RS-232 cable for troubleshooting RS-232 connections.

Campbell Scientific offers three RS-232 cables that support different data loggers or wiring configurations. Refer to Table 7-3 (p. 14) for the cable descriptions, compatible data loggers, and the data logger connections.

8.3 Check SC105 baud rate settings

If using an SC105 on the CS I/O port, verify the following:

1. Use the SC12 cable to connect the data logger **CS I/O** port to the SC105 **CS I/O** port and connect the data logger to a power supply.

- 2. Use the socket null modem serial cable to connect the SC105 to the computer.
- 3. Open *Device Configuration Utility*.
- 4. Type SC105 in the **Device Type** box and click **SC105**.
- 5. Select the **Communication Port** on the computer to which the SC105 is connected.
- 6. Click Connect.
- 7. Ensure the CS I/O ME Baud Rate and Baud Rate settings are 9600.

evice Type	Deployment Settings Editor
🞗 Search 🛞	SC105 Settings
SC105	Serial Number: 1
Camera	CS T/O Mode: SDC &ddrees 7
CCEP	
Cellular Modem	CS L/O ME Baud Kate: 99000 V
LS300	RS-232 Mode: Modem (default) ~
Raven XT	Baud Rate: 9600 (default) V Parity: None (default) V
Datalogger	Stop Bits: 1 bit (default) V Data Bits: 8 bits (default) V
CR1000	
CR 1000X Series	RS-232 Mode
CR300 Series	This setting allows control over how the DTR and RTS lines behave. DTR is on pin 4 of the RS-232 connector; RTS is on pin 7.
CR3000	PC/PDA Mode
CR350 Series	C/PDA mode DTR & RTS are both driven to 5V.
CR6 Series	Modem Mode
Connection Type	after DTR & RTS are dropped of 2 sec when data coming in on the RS-232 port will be ignored.
Direct IP	Custom mode
ommunication Port (j)	Inis mode is similar to the violoem wode, except that KTS will key the data. While DTR remains HI, KTS will be HI only while data is being sent out the RS-232 port. The delays are programmable between RTS HI and data, data and RTS LO, and the 'dead time'. For SDC Address 7, 8, 10, or 11, DTR will always be driven to +5v.
UM1 V	
aud Rate (i)	
600 🗸	

8. Click **Apply** if the baud rate values were changed.

8.4 Check mounting and connections for the antennas

Verify that both the GPS and transmitter antennas are mounted correctly, and securely attached to the correct connector on the TX325. The GPS antenna cable has an SMA connector that fastens to the **GPS** port of the TX325. The transmitter antenna connects to the **RF Out** port on the TX325.

Visually inspect both antenna cables looking for breaks, frayed wires, and corrosion on the connectors and ports.

Valid GPS antennas include the following. Refer to www.campbellsci.com/order/tx325 1 for more information.

• 27 dBi GPS Antenna with Magnetic Mount and cable: This antenna is for applications where signal strength is strong and the likelihood of snow is low.



• 28 dBi GPS Antenna, Jam Resistant: This antenna is better for all weather conditions and for applications where a weak GPS signal may be present. This antenna requires the purchase of an GPS antenna cable.



NOTE:

If using surge protection with the GPS antenna verify the surge protector is DC coupled so that it can supply power to the antenna. Campbell Scientific offers a suitable kit (www.campbellsci.com/order/tx325 \Box).

For the transmitter antenna, Campbell Scientific recommends using the GOES Yagi RHCP Antenna listed on the website (www.campbellsci.com/order/tx325 \square).

Refer to Data collection platform (DCP) installation (p. 5) for instructions about correctly mounting the GPS and transmitter antennas.

8.5 Verify antenna positioning

Verify the GPS antenna has a clear view of most of the sky and the transmission antenna has a clear view of the satellite. The ideal location for the GPS antenna is high enough to be above everything, but with the shortest cable possible. Cement, steel roofing, or steel walls will restrict or prevent GPS communications.

Check that the transmitter antenna is properly aimed. A poorly aimed antenna will cause a drop in signal strength or possibly prevent successful transmission. As a guide, if the antenna is aimed

20 degrees off the spacecraft, the received power will be half of a properly aimed antenna. Beyond 20 degrees, the received power drops off quickly.

The *Device Configuration Utility* software has a tool for helping to point the transmitter antenna. Refer to Transmission antenna (p. 15) for more information.

8.6 Verify GPS fix

Ensure that the TX325 has a valid GPS fix. For the newer data loggers, use the data logger **GOES** tab in the *Device Configuration Utility*, and check the diagnostics at the bottom of the screen.

GOES Enabled			
GOES COM Port: RS-232			
OES Platform ID: 12345678			
ES Antenna Gain 0			
GOES Time: 2022-03-31 20:30:17.8			
If Timed TX Options	Random TX Options		
Channel: 195	Channel: 195	Channel: 195	
BAUD Rate: 300 BPS - GOES 🗸	BAUD Rate: 300 BPS - GOES V	BAUD Rate: 300 BPS - GOES V	
TX Rate: 0 :1 :0 :0	TX Rate: 1 :0 :0		
Offset Time: 0 = :0 = :0	Penest Count: 2		
TX Window: 10			
TX Window: 10			
TX Window: 10]	
TX Window: 10 •			
TX Window: 10 - General Radio Status OS Version: 10:25:03 04/23/2020 Fold of Status To 25:03 04/23/2020			
TX Window: 10 General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe P	has not been tripped.		
TX Window: 10 General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe P Radio Temperature: 20 °C	has not been tripped.		
TX Window: 10	has not been tripped.		
TX Window: 10 C General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe b Radio Temperature: 20 °C Current Battery: 13.464 V Last Transmission Status	has not been tripped.		
TX Window: 10 C General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe P Radio Temperature: 20 °C Current Battery: 13.464 V Last Transmission Status Status:	has not been tripped. GPS Status Antenna Status: Antenna is OK.		
TX Window: 10 General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio 1s OK. Failsafe P Radio Temperature: 20 °C Current Battery: 13.464 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V	has not been tripped. GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GFS fix.		
TX Window: 10 C General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio 1s 0K. Failsafe E Radio Temperature: 20 °C Current Battery: 13.464 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V Battery Volts During TX: 13.242 V	has not been tripped. GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GPS fix. Last Fix Time: 2022-03-31 09:23:27		
TX Window: 10 General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio 1s 0K. Failsafe P Radio Temperature: 20 °C Current Battery: 13.464 V Last Transmission Status Status: Battery Volts Defore TX: 13.414 V Battery Volts During TX: 13.242 V Duration: 1740 msec	has not been tripped. GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GPS fix. Last Fix Time: 2022-03-31 09:23:27 Number of Missed Fixes: 0		
TX Window: 10 C General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio 1s OK. Failsafe P Radio Temperature: 20 °C Current Battery: 13.464 V Last Transmission Status Status: Battery Volts Before TX: 13.414 V Battery Volts During TX: 13.242 V Duration: 1740 msec Forward Power: 0.75 W	has not been tripped. GPS Status Antenna Status: Antenna is OK. Acquisition Status: The GOES radio has a valid GPS fix. Last Fix Time: 2022-03-31 09:23:27 Number of Missed Fixes: 0 Location: Lat 41.76335, Long -111.85755, Alt 901.6 m		

8.7 Verify data logger operating system (OS) is compatible

The following table lists the data logger operating systems that are compatible with the TX325 transmitter:

Table 8-1: Compatible data logger operations systems			
Data logger	Operations system		
CR1000X	6.02 or newer		
CR6	12.02 or Newer		
CR300-series	10.08 or Newer		
CR350	1.05 or Newer		
CR1000/CR800/CR3000	32.06 or Newer		

To verify the data logger OS version, connect to the data logger using the *Device Configuration Utility* and navigate to **Deployment** > **Datalogger** > **OS Version**.

8.8 Check TX325 settings

GOES radio settings are typically set in the data logger program, but can be verified in the *Device Configuration Utility* or through LoggerNet > Connect > Datalogger > Settings Editor.

NOTE:

Change the settings in the data logger program because the data logger program will reset the *Device Configuration Utility* settings.

In the *Device Configuration Utility* software, click the GOES tab:

- 1. Access the Device Configuration Utility.
- 2. Select your data logger in Device Type.
- 3. Under **Deployment**, click the **GOES** tab.

NOTE:

The GOES tab is not available for the CR3000, CR1000, and CR800 Series.

- 4. Verify the GOES Enabled box is checked.
- 5. Ensure that the eight digit GOES Platform ID is correct.
- 6. The GOES Antenna Gain setting should be the default value of 0 when using the standard Yagi antenna offered by Campbell Scientific. Only change this value if using a user-supplied antenna (refer to Antenna gain for nonstandard antennas (p. 67) for more information).
- 7. Verify that the Self-Timed BAUD Rate is correct.
- 8. Ensure that the **Self-Timed Channel** is correct.
- 9. Verify that the Self-Timed TX Interval is correct and in the format of dd:hh:mm:ss.

- 10. Verify that the Self-Timed TX Offset is correct and in the format of hh:mm:ss.
- 11. If applicable, verify that the Random TX BAUD Rate is correct.
- 12. If applicable, verify that the Random TX Channel is correct.
- 13. If applicable, verify that the **Random TX Rate** has been applied and that the format is hh:mm:ss.
- 14. Click the COM Port Settings tab.
- 15. Ensure that the **ComPort** setting matches the communications port in which the TX325 is connected.
- 16. Verify that the **BAUD Rate** is 9600.

8.9 Check data logger program

CAUTION:

Data logger programs for an older GOES radio such as the TX312, TX320, or TX321 will not work with a TX325.

Verify the data logger program is structured for the correct data logger model. The CRBasic program for newer data loggers (CR1000X, CR6, CR350, CR300-series) is different and not interchangeable with the CRBasic program for older data loggers (CR3000, CR1000, CR800-series). Example programs for the newer and older data loggers are available at www.campbellsci.com/tx325

NOTE:

If converting from using an older TX321 radio to a newer TX325, you will have to make significant changes to your program. Refer to TX321 program converted to TX325 program (CR1000, CR3000, CR800-series) (p. 69) for more information.

Find the **ConstTable** near the top of your data logger program. Check the values in this table to ensure that they are entered correctly. These values include but are not limited to the following:

Table 8-2: Constant table parameters		
Constant	Description	
Const GOES_COMPORT	Generally COMRS232 depending on data logger	
Const GOES_ID	Is a unique value that is also called the DCP ID. Value must be in quotes.	

Table 8-2: Constant table parameters		
Constant	Description	
Const UTC_OFFSET	Number of seconds from the UTC time. – 25200 is mountain time.	
Const SELF_TIMED_CHANNEL	Also called the Primary Channel.	
Const SELF_TIMED_BAUD_RATE	DCS assigns either 300 or 1200	
Const SELF_TIMED_INTERVAL	Must be in quotes. Format is DD:HH:MM:SS	
Const SELF_TIMED_OFFSET	Must be in quotes. Format is DD:HH:MM:SS	
Const SELF_TIMED_WINDOW	DCS calls this window. Size of TX window	
Const RANDOM_CHANNEL	Also called the Secondary Channel.	
Const RANDOM_BAUD_RATE	DCS assigns either 300 or 1200	
Const RANDOM_INTERVAL	Must be in quotes. Format is DD:HH:MM:SS	
Const RANDOM_OFFSET	Must be in quotes. Format is DD:HH:MM:SS	
Const RANDOM_WINDOW	DCS calls this window. Size of TX window	
Const DATA_FORMAT	Generally either pseudo binary or ASCII data	
Const NUMBER_OF_VALUES_TO_TX	The number of values you transmit to DCS for each variable. By default this will send 4 values for each variable one for each 15 min interval during the hour.	

Comments in the example programs will provide guidance on the valid parameters for these fields. Also, refer to the information provided by the NOAA DCS system. This information is unique for each GOES connection.

8.10 Check for fail-safe mode

The TX325 transmitter will go into the fail-safe mode if one of two events occurs:

- 1. The transmitter RF output is turned on and left on for more than 110 seconds.
- 2. The transmitter is given a command to transmit less than 30 seconds after a transmission has taken place.

If a fail-safe condition occurs, the red fail-safe LED is on continuously; the RF output is disabled; and the microprocessor is reset, causing the transmitter to restart. While in the fail-safe mode,
the transmitter can communicate normally with the data logger, but is unable to transmit until the fail-safe mode has been cleared.

There are two ways to check if the TX325 is in fail-safe mode. The first is on site by checking the red fail-safe LED on the TX325 (see LED function [p. 12]). The fail-safe LED is located above the **Reset** button in the side of the transmitter housing (Figure 8-1 [p. 33]). If the red LED is on continuously, the radio is in fail-safe mode.



Figure 8-1. Reset button and fail-safe LED location

The fail-safe mode can also be checked using the *Device Configuration Utility*. To use this method, connect to the data logger and click the **Deployment** > **GOES** tab. The **Fail-safe Status** is displayed in the **General Radio Status** section of the screen.

Deployment Settings Editor	
Datalogger Com Ports Settings Ethernet CS I/O IP PPP GOES	Network Services TLS Advanced
General Radio Options GOES Enabled GOES COM Port: RS-232 ~ GOES Platform ID: 12345678 GOES Antenna Gain 0 ~ GOES Time: 2022-03-31 20:20:00.7	
Self Timed TX Options Channel: 197 💌 BAUD Rate: 1200 BPS - GOES TX Rate: 0 🔹 :1 🌨 :0 :0 TX Offset Time: 0 :20 :0 TX Window: 10	Random TX Options Channel: 195 • BAUD Rate: 300 BPS - GOES TX Rate: 0 • :30 • :0 • Repeat Count: 1 •
General Radio Status OS Version: 10:25:03 04/23/2020 Fail-safe Status: Radio is OK. Failsafe has Radio Temperature: 20 °C Current Battery: 13.494 V	not been tripped.

The only way to reset the fail-safe mode is to push the Reset button (Figure 8-1 [p. 33]).

CAUTION:

A power cycle will not clear the fail-safe mode.

8.11 Watch RS-232 transmission

The following instructions show the process of using the terminal mode in the *Device Configuration Utility* to watch the RS-232 traffic to ensure that the data logger and TX325 GOES radio are communicating with each other:

- 1. Connect the data logger to the computer and access the *Device Configuration Utility*.
- 2. Click the Terminal tab.
- 3. Press enter until **CR1000X>** (or a different data logger model) is displayed.
- 4. Type W and press Enter.
- 5. Type the RS-232 port number and press Enter.

6. When prompted for ASCII (Y), type N for no and press Enter.

CR1000X>W 1: ComRS232 2: ComME 3: Com310 4: ComSDC7 5: ComSDC8 6: Com320 7: ComSDC10 8: ComSDC11 9: ComCl 10: ComC3 11: ComC5 12: ComC7 13: ComUSB 15: TCP/IP 16: SDM-SI04 17: Ethernet 22: USB network 23: IP Trace 32...47: SDM-SIO1 Select: 1 ASCII (Y)? N opening 1 hit ESC to exit, any other key to renew timeout

7. After entering the communications watch mode for the GOES interface, either trigger the GOES communication or wait for a transmission to take place.

The data logger time is displayed on the left in the hh:mm:ss.sss format. After the time, either a T or an R is displayed. T indicates that the data logger is transmitting data to the GOES radio and R indicates that the data logger is receiving data from the GOES radio. After the T or R, the transmitted data is displayed.

NOTE:

If you answered Y for step 6, you wouldn't be able to read the raw data in the Terminal mode

The following shows an example RF traffic screen:

12:10:00.536 R 00 00 00 00 00 00 00 0B 12:10:00.546 R 7C 23 FE FF 60 15 23 FE |#..`.#. 12:10:00.556 R FF 80 12 00 43 00 43 23C.C# 12:10:00.566 R FB 02 23 FE 66 00 00 23 ..#.f..# 12:10:00.576 R FE DF 00 00 20 00 10 13 12:10:00.586 R 05 0A 00 00 C3 23 FE 00 12:10:00.596 R 4C 20 00 00 D7 04 L 12:10:07.053 T 01 00 1F 1F 04 12:10:07.063 R 01 02 F0 ... 12:10:07.073 R 23 FB F6 04 **#**... 12:10:07.093 T 01 00 14 14 04 12:10:07.103 R 01 0A 14 . . . 12:10:07.113 R 00 00 20 00 10 13 0A 07 12:10:07.123 R 23 FE 73 04 #.s. 12:10:07.120 T 01 00 10 00 10 04 12:10:07.130 R 01 06 . . 12:10:07.140 R 10 00 23 FE 23 FB D2 F0 12:10:07.150 R DD 04 12:10:07.170 T 01 00 1E 00 00 20 00 10 13 0A 0A 00 4E 55 4C 4C NULL 12:10:07.170 T 2E 44 41 54 00 00 00 00 00 00 00 00 00 00 C3 00 .DAT..... 12:10:07.170 T 00 0D 0A 31 33 2E 36 31 32 2C 31 33 2E 36 31 34 ...13.612,13.614 12:10:07.170 T 2C 31 33 2E 36 33 36 2C 31 33 2E 36 33 34 2C 31 ,13.636,13.634,1 12:10:07.170 T 33 2E 36 31 36 2C 0D 0A 32 34 2E 36 30 33 2C 32 3.616,..24.603,2 12:10:07.170 T 34 2E 35 38 37 2C 32 34 2E 35 37 32 2C 32 34 2E 4.587,24.572,24. 12:10:07.170 T 35 35 39 2C 32 34 2E 35 34 35 2C 0D 0A AB 04 559,24.545,.... 12:10:07.330 R 01 02 1E 00 20 04

A full set of test results from a sniff showing the communications between the TX325 and a data logger is available in Watch test results (p. 65).

8.12 Diagnostic table

This summary of the most relevant diagnostic values contained in the **GOES_DIAGNOSTICS** table can help users troubleshoot communications.

Low power is a common issue. The following diagnostic values can indicate power issues. Refer to Check TX325 and data logger power (p. 25) for more information.

- goes_battery: Current GOES battery voltage. For the 12 V data logger system, this always needs to stay at 12 V or more.
- goes_battery_before_tx: System voltage before transmission. This value should be 12 V or higher.

• **goes_battery_during_tx**: System voltage during transmission. A value below 12 V indicates power problems and that the power sources (battery, solar panel) will be unable to provide enough power for transmission.

The following diagnostic values can indicate problems in getting a GPS fix, which is likely a GPS antenna issue. For more information, refer to Check mounting and connections for the antennas (p. 27) and Verify antenna positioning (p. 28).

- **goes_time_last_gps_position**: The GOES time and GPS position of the last GPS fix. The TX325 can operate for a few days without a current GPS fix, but will eventually fail.
- goes_number_of_missed_gps: The number of attempts that failed to get a GPS fix. A high number indicates a poor GPS signal.

NOTE: The TX325 does not require a new GPS fix each day.

- goes_time_last_missed_gps_fix: The last time a GPS fix attempt was missed.
- goes_gps_acquisitions_status: The current status of the GPS fix attempt.

The following are used to troubleshoot issues with the RF Out cable or transmitter antenna. For antenna help, refer to Check mounting and connections for the antennas (p. 27) and Verify antenna positioning (p. 28).

- goes_forward_tx_power: GOES forward TX Power in Watts. The values contained in the Forward RF Power field are approximate measurements, intended to help diagnose antenna and RF cable issues. These values can also be affected by antenna impedance and antenna cable characteristics. The range is 0 to 4 W. A value of 0 indicates a problem. If the values are too low, check the transmitter antenna.
- **goes_reflected_rf_power**: GOES Reflected RF Power in watts. The values contained in the Reflected RF Power field are approximate measurements, intended for use in detecting and diagnosing antenna and RF cable issues. These values can also be affected by antenna impedance and antenna cable characteristics. A value over 1 indicates a problem. If the values are too high, check the transmitter antenna.

NOTE:

The CR1000, CR800 series, and CR3000 data loggers do not provide Forward and Reflective Power in the GOES Diagnostics Table.

- **goes_vswr**: Voltage standing wave ratio (VSWR) is a ratio of the forward and reflected power. The VSWR values indicate the following:
 - VSWR < 2.0 indicates a good connection between transmitter and antenna.
 - VSWR between 2.0 and 3.0 possibly indicates a poor connection. Check the cables.
 - VSWR > 3.0 indicates a poor connection between transmitter and antenna. The cable might be damaged or disconnected.

The following are a couple of other relevant diagnostic values contained in the **GOES_ DIAGNOSTICS** table:

- goes_fail_safe_indicator: Shows whether the fail safe has been triggered. For information about resetting the fail safe, refer to Check for fail-safe mode (p. 32).
- goes_tx_result_code: These codes provide likely reasons that data was not output to the TX325 transmitter. The following result codes are also available using the GOESTable CRBasic instruction:
 - "No Output"
 - "Write error"
 - ° "Timed out waiting for STX character from transmitter after SDC addressing"
 - "Wrong character received after SDC addressing"
 - "Timed out waiting for ACK or OK"
 - "CS I/O port not available; GOES not attached"
 - "Buffer Control Error"
 - "COM9602 not communicating"
 - "Illegal data format"
 - "Transmitter not set up"

8.13 Troubleshooting over-air transmissions

TX325 users within the GOES system can troubleshoot their over-the-air data transmissions by using one of the following websites:

- https://dcs1.noaa.gov/Account/FieldTest
- https://dcs2.noaa.gov/Account/FieldTest
- https://dcs3.noaa.gov/Account/FieldTest
- https://dcs4.noaa.gov/Account/FieldTest ☑

The DCS Field Test with your GOES connection will return information about the platform and any message data found in the date/time range specified by the query. If values are displayed after performing the DCS field test, the GOES transmitter is sending data to the DCS system. If the received values are within the acceptable parameters, the connection is working well.

- 1. Type your eight-character GOES Platform ID in the PLATFORM field.
- 2. Type the **START DATE**.
- 3. Type the END DATE.
- 4. Select the number of hours you want the field test system to go back to.
- 5. Type the **USERNAME** and **PASSWORD**.
- 6. Click SUBMIT.

0	JES DESTILED TEST	
PLATFORM		
START DATE	01/15/2024	
END DATE	01/15/2024	
	1 HOUR 🗸	
USERNAME	[ENTER USERNAME]	
PASSWORD	[ENTER PASSWORD]	

The top of the output shows the assigned GOES Platform ID (**Group**), channels (**PChan**, **SChan**), transmission times (**First**, **Period**), and window length (**Window**). Make sure your settings in your DCP match this information. Failure to do so will result in loss of data and transmitting over the top of other DCP scheduled slots and also will result in the loss of other user data.

 Group:
 CAMSCI
 PChan:
 3
 SChan:
 121
 First:
 00:16:50
 Period:
 01:00:00
 Window:
 00:00:10

The bottom table shows information that can help determine the health of the DCP transmissions. Example results:.

roup: CAMSCI			PChan: 195		195 SChan:			First: 00:00:00			00:00:00 Period: 00:00:00 Window: 00:00:00		
Addr	Chan	Baud	Sig	Phs	Qual	Freq	Car	End	AR	MSID	Туре	Len	n Data
00000000	195	300	35.7	3.20	99.1	0.1	1/16/2024 19:05:10	1/16/2024 19:05:13	G	16	C52	77	13.631,13.634,13.634,13.634,13.617, 24.530,24.515,24.498,24.479,24.458,
00000000	195	300	35.5	3.28	98.8	0.0	1/16/2024 19:00:10	1/16/2024 19:00:13	G	16	CS2	77	13.634,13.633,13.634,13.634,13.616, 24.435,24.409,24.381,24.350,24.318,
00000000	195	300	34.9	3.26	98.5	0.2	1/16/2024 18:55:10	1/16/2024 18:55:13	G	16	CS2	77	13.613,13.612,13.613,13.613,13.616, 24.285,24.251,24.216,24.181,24.144,
00000000	195	300	34.7	4.01	98.8	0.5	1/16/2024 18:50:10	1/16/2024 18:50:13	G	16	CS2	77	" 13.616,/////,/////,/////, 24.106,/////,/////,////////////////////////

Field descriptions of DCS results:

- Addr: GOES Platform ID
- Chan: GOES channel that the transmission used.
- Baud: Baud rate of the transmission. Either 300 or 1200.
- Sig: Signal strength, which should be in a range of 25 to 56. If the received Sig is too low (under 25), transmissions won't meet the reception threshold to communicate and the connection will not be reliable. Sig over 56 is a violation of the user certification and user agreement and will increase noise for other users who might be transmitting. Ideally, for 300 baud, the signal strength should be around 42.
- Phs: Phase that should be near 0 or a low single digit.
- Qual: Signal quality in percent that should be in the 90s.
- Freq: Frequency offset of the transmission indicates how far outside of the channel center frequency that the transmission was at. DCS allows plus or minus 150 Hz from the channel center. Messages outside the limit will not be received by the satellite. Significant deviation in Freq usually is caused by a faulty transmitter.

An extra character could be in front of the transmitted data message, indicating whether or not the GPS time synced (Table 8-3 [p. 40]). This character is added to the number of bytes (shown as LEN) that were in the data transmission.

Table 8-3: Characters indicating time sync									
Character	Data type	Time synced since last transmission							
Space	ASCII	No							
Double quote (")	ASCII	Yes							
Apostrophe (')	Binary	No							
Lower case b	Binary	Yes							

NOTE:

If values in DCS or the **GOES_Data** table are showing as NAN, INF, -7999, +7999, or a series of forward slashes (/) instead of measurement values, either the system is having trouble making a good sensor measurement or there is a problem with the variable types in your data table. For variable type issues see Data formats and transmission durations (p. 43).

8.14 Verify GOES service and check GOES data

If it has been a while since accessing the GOES service or the station has frequently violated the timing window, the GOES service may not be active. To verify that your GOES service is still active, go to https://dcs2.noaa.gov 1 then contact DADDS Technical Support/Customer Service using the online information.

LoggerNet does not interface directly with GOES. Users can get data from the GOES system through NOAA by logging into https://dcs4.noaa.gov/Account/Login and or using the *LRGS Client* software also called *OPEN DCS*. The client *OPEN DCS* allows the data to be downloaded to a local computer. A *Getting Started Guide* for the client is available on the GOES website (https://dcs3.noaa.gov/LRGS/LRGS-Client-Getting-Started.pdf).

For variable type issues or trouble getting good sensor values, refer to Data formats and transmission durations (p. 43).

Appendix A. Eligibility and getting onto the GOES system

U.S. federal, state, or local government agencies, or users sponsored by one of those agencies, may use GOES. Potential GOES users must apply for and be granted a System Use Agreement (SUA) by NESDIS, which is typically renewable every 5 years. Use the following procedure to acquire permission for getting onto the GOES system:

- 1. Follow the steps provided at: https://dcs2.noaa.gov ☐ to submit an application for GOES DCS SUA. Once submitted, the approving authorities will review the application and notify you within two weeks. If you are approved NESDIS will send you a *Memorandum of Agreement (MOA)*.
- 2. Sign and submit the MOA. After the MOA is approved, NESDIS will issue a channel assignment and an GOES platform ID.
- 3. **IMPORTANT:** Contact NESDIS to coordinate a start-up date.

See https://dcs2.noaa.gov d for more information.

Appendix B. Data formats and transmission durations

Data transmissions are generally described as having an ASCII or pseudobinary format. The particular nature of how the data is formatted prior to sending the data over-the-air. The data order in those transmissions is determined by the content and organization of the DataTables() and execution of GOESTable() and GOESField(). Scan-order (interleaved) and channel-order data can be sent by using an ASCII or pseudobinary format with one of the native data logger data format options. The flexibility of CRBasic allows virtually any message type to match the decode system requirements.

B.1 ASCII data format

ASCII data formats are used to transmit data in plain readable text. This format is widely used for random or alert transmissions. They can be used for self-timed messages. Several standard formats are selectable within CRBasic. Formats not included can be easily formed using string-formatted data fields, allowing the content to be tailored to your application needs. String-formatted data fields are limited to 13 characters for each field.

B.1.1 7-byte floating-point ASCII (GOESTable() format option 1)

The 7-byte floating-point ASCII data type is a fixed-width format with variable precision.

- Operating range of ±7999, depending on placement of decimal point (see Table B-1 [p. 44]).
- Variable precision of 0.001 to 1, depending on placement of decimal point (see Table B-1 [p. 44]).
- Precision (placement of decimal point) is automatically determined based on the magnitude of the value (Table B-1 [p. 44]).
- Number are rounded to selected precision during conversion. For example, +12.345, will be rounded to +12.35.
- Value is always 7 characters including a trailing comma.
- Value is always signed (+/-).

- Leading zeros and trailing zeros are added to maintain the width (7 characters) of the value transmitted.
- Value always has a trailing comma. This includes the last value sent.
- Valid data outside of operating range are set to –7999 or +7999, unless it is a NAN, +INF, or -INF (see Table B-1 [p. 44]).

Table B-1: 7-byte floating-point ASCII data										
Range	Maximum precision	Example ASCII output								
±7.999	0.001	+1.200,								
±79.99	0.01	+12.00,								
±799.9	0.1	+120.0,								
±7999	1	+1200.,								
	$NAN^{1} = -8190$).,								
	$+1NF^{2} = +819^{2}$	1.,								
	-INF ² = -8191	•1								
¹ Not A Number										
² Infinity	² Infinity									

Example output (with 10 fields):

```
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 1
GoesField() Decimation = 1
        <CR><LF>-7994.,-7994.,+8191.,-8191.,-8190.,+8191.,-8191.,-8190.,+13.10,+27.32,
```

```
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 1
GoesField() Decimation = 4
        <CR><LF>-7997.,-7997.,+8191.,-8191.,-8190.,+8191.,-8191.,-8190.,+13.15,+26.08,
        <CR><LF>-7996.,-7996.,+8191.,-8191.,-8190.,+8191.,-8191.,-8190.,+13.16,+26.04,
        <CR><LF>-7995.,-7995.,+8191.,-8191.,-8190.,+8191.,-8191.,-8191.,-8190.,+13.17,+26.03,
        <CR><LF>-7994.,-7994.,+8191.,-8191.,-8190.,+8191.,-8191.,-8191.,-8190.,+13.19,+26.18,
```

```
GoesTable() Fields_Scan_Order = True, Newest_First=FALSE, Format = 1
GoesField() Decimation = 1
   <CR><LF> -7994.,
   <CR><LF> -7994.,
   <CR><LF> +8191.,
   <CR><LF> -8191.,
   <CR><LF> -8190..
   <CR><LF> +8191.,
   <CR><LF> -8191.,
   <CR><LF> -8190.,
   <CR><LF> +13.13,
   <CR><LF> +27.72,
GoesTable() Fields_Scan_Order = True, Newest_First=FALSE, Format = 1
GoesField() Decimation = 4
   <CR><LF>-7997., -7996., -7995., -7994.,
   <CR><LF>-7997., -7996., -7995., -7994.,
   <CR><LF>+8191.,+8191.,+8191.,+8191.,
   <CR><LF>-8191., -8191., -8191., -8191.,
   <CR><LF>-8190., -8190., -8190., -8190.
   <CR><LF>,+8191.,+8191.,+8191.,+8191.,
   <CR><LF>-8191.,-8191.,-8191.,-8191.,
   <CR><LF>-8190., -8190., -8190., -8190.,
   <CR><LF>+13.12,+13.12,+13.12,+13.11,
   <CR><LF>+27.59,+27.59,+27.59,+27.60,
```

B.1.2 ASCII table space (GOESTable() format option 2)

This option provides a tabular format. Columns are fixed width, according to the field format, and are space delimited. Lines are <CR> <LF> delimited. You can send either the newest or oldest data first. A <CR> <LF> is added at the end of the final line sent.

- NANs, +INFs, -INFs, and missing values show as forward slashes (/) in the output.
- Each line contains all the values listed in GOESTable() that have been set with GOESField() and are sent in the order they are listed in the data table if Scan_Order is set to False.
- Each line has all data from a single sensor if Scan_Order is set to True.
- SHEF Codes can be added as headers or at the beginning of lines using GOESField() option SHEF.
- Value has a fixed width (Table B-2 [p. 46]).
- Value has a fixed precision (Table B-2 [p. 46]).
- Value only has a leading sign when negative (-).

- Data outside of operating range will be set to the minimum or maximum of the range.
- Value always has a trailing space character.

Table B-2: ASCII format, width, precision, and range												
Format	Width	Precision	Range	Example ASCII output containing two values								
xxx	3	1	-99 to 999	012 -34								
xxxxx	5	1	-9999 to 99999	00012 -0034								
xxx.x	5	0.1	-99.9 to 999.9	001.2 -03.4								
xx.xx	5	0.01	-9.99 to 99.99	00.12 -0.34								
x.xxx	5	0.001	999 to 9.999	0.012034								

Example outputs (with 10 fields):

```
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 1, Precision = 3, Width = 4
        <CR><LF>-7.982 -7.982 //// //// //// //// 13.1 25.8<CR><LF>
```

```
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 4, Precision = 3, Width = 5
        <CR><LF>-9.81 -9.81 //// //// //// //// //// 13.15 26.08
        <CR><LF>-9.80 -9.80 //// //// //// //// 13.13 26.08
        <CR><LF>-9.79 -9.79 //// //// //// //// 13.14 26.08
        <CR><LF>-9.78 -9.78 //// //// //// //// 13.14 26.08<CR><LF>
```

```
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 4, Precision = 3, Width = 5
   <CR><LF>-9.45 -9.44 -9.43 -9.42
   <CR><LF>-9.45 -9.44 -9.43 -9.42
   <CR><LF>//// ///// /////
   <CR><LF>//// ///// /////
   <CR><LF>//// ///// ///// /////
   <CR><LF>//// ///// ///// /////
   <CR><LF>//// ///// ///// /////
   <CR><LF>//// ///// /////
   <CR><LF>13.13 13.14 13.13 13.13
   <CR><LF>26.24 26.24 26.24 26.24
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 1, Precision = 3, Width = 5, SHEF set to HG, TA, VB
   <CR><LF>HG TA VB
   <CR><LF>-7.94 13.13 26.72<CR><LF>
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 4, Precision = 3, Width = 5, SHEF set to HG, TA, VB
   <CR><LF>HG TA VB
   <CR><LF>-8.32 13.14 26.74
   <CR><LF>-8.31 13.14 26.74
   <CR><LF>-8.30 13.14 26.74
   <CR><LF>-8.29 13.14 26.74<CR><LF>
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 1, Precision = 3, Width = 5, SHEF set to HG, TA, VB
   <CR><LF>HG -6.79
   <CR><LF>TA 13.12
   <CR><LF>VB 26.68<CR><LF>
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 4, Precision = 3, Width = 5, SHEF set to HG, TA, VB
   <CR><LF>HG -8.26 -8.25 -8.24 -8.23
   <CR><LF>TA 13.14 13.14 13.13 13.14
   <CR><LF>VB 26.76 26.76 26.76 26.76
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 2
GoesField() Decimation = 4, Precision = 3, Width = 5, SHEF set to HG, TA, VB
  NOTE:
  To get a single battery voltage (or other additional data), set GoesField() Decimation =
```

1 for just the **battery_voltage** (or other) value in the **GOESTable()**.

```
<CR><LF>HG -9.70 -9.69 -9.68 -9.67
<CR><LF>TA 13.11 13.13 13.10 13.13
<CR><LF>VB 26.82 26.82 26.82 26.82
<CR><LF>BATTERY 13.13
<CR><LF>DATE 200336
<CR><LF>TIME 101500<CR><LF>
```

B.1.3 ASCII table space, comma separated (GOESTable() format option 3)

This option provides a tabular format. Columns are fixed width, according to the field format, and are comma (,) delimited. Lines are <CR><LF> delimited. You can send either the newest or oldest data first. A <CR><LF> is added at the end of the final line sent.

- NANs, +INFs, -INFs, and missing values show as forward slashes (/) in the output.
- Each line contains all the values listed in GOESTable() that have been set with GOESField() and are sent in the order they are listed in the data table if Scan_Order is set to False.
- Each line has all data from a single sensor if **Scan_Order** is set to **True**.
- SHEF Codes can be added as headers or at the beginning of lines using GOESField() option SHEF.
- Value has a fixed width (Table B-2 [p. 46]).
- Value has a fixed precision (Table B-2 [p. 46]).
- Value only has a leading sign when negative (-).
- Data outside of operating range will be set to the minimum or maximum of the range.
- Value always has a trailing comma (,).

Example outputs (with 10 fields):

```
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 1, Precision = 3, Width = 4
        <CR><LF>-7.982,-7.982,///,///,///,///,///,///,13.1,25.8<CR><LF>
```

```
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 4, Precision = 3, Width = 5
        <CR><LF>-9.81,-9.81,////,////,////,////,////,13.15,26.08
        <CR><LF>-9.80,-9.80,////,////,////,////,13.13,26.08
        <CR><LF>-9.79,-9.79,////,////,////,////,13.14,26.08
        <CR><LF>-9.78,-9.78,-9.78,////,////,////,////,13.14,26.08
```

```
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 1, Precision = 3, Width = 5
   <CR><LF>-9.68
   <CR><LF>-9.68
   <CR><LF>/////
   <CR><LF>/////
   <CR><LF>/////
   <CR><LF>/////
   <CR><LF>/////
   <CR><LF>/////
   <CR><LF>13.12
   <CR><LF>26.43<CR><LF>
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 4, Precision = 3, Width = 5
   <CR><LF>-9.45, -9.44, -9.43, -9.42
   <CR><LF>-9.45, -9.44, -9.43, -9.42
   <CR><LF>////,////,/////,/////
   <CR><LF>////,////,/////,/////
   <CR><LF>////,////,/////,/////
   <CR><LF>////,////,////,/////
   <CR><LF>////,////,////,/////
   <CR><LF>13.13,13.14,13.13,13.13
   <CR><LF>26.24,26.24,26.24,26.24<CR><LF>
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 1, Precision = 3, Width = 5, SHEF set to HG, TA, VB
   <CR><LF>HG, TA, VB
   <CR><LF>-7.94,13.13,26.72<CR><LF>
GoesTable() Fields_Scan_Order = FALSE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 4, Precision = 3, Width = 5, SHEF set to HG, TA, VB
   <CR><LF>HG, TA, VB
   <CR><LF>-8.32,13.14,26.74
   <CR><LF>-8.31,13.14,26.74
   <CR><LF>-8.30,13.14,26.74
   <CR><LF>-8.29,13.14,26.74<CR><LF>
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 1, Precision = 3, Width = 5, SHEF set to HG, TA, VB
   <CR><LF>HG, -6.79
   <CR><LF>TA,13.12
   <CR><LF>VB,26.68<CR><LF>
```

```
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 3
GoesField() Decimation = 4, Precision = 3, Width = 5, SHEF set to HG, TA, VB
```

NOTE:

To get a single battery voltage (or other additional data), set **GoesField()** Decimation = 1 for just the **battery_voltage** (or other) value in the **GOESTable()**.

```
<CR><LF>HG, -9.70, -9.69, -9.68, -9.67
<CR><LF>TA, 13.11, 13.13, 13.10, 13.13
<CR><LF>VB, 26.82, 26.82, 26.82, 26.82
<CR><LF>BATTERY, 13.13
<CR><LF>DATE, 200336
<CR><LF>TIME, 101500<CR><LF>
```

B.1.4 Line SHEF (GOESTable() format option 6)

ASCII output using standardized SHEF codes in a format that is human readable.

- NANs, +INFs, -INFs, and missing values show as forward slashes (/) in the output.
- LABEL is the SHEF code (two character) parameter. Refer to https://dcs1.noaa.gov/documents/SHEF%20Codes.pdf ☐ for details on SHEF codes.
- OFFSET is how long ago the sensor reading was made and stored in the GOESTable() data table and is reported in number of minutes.
- INTERVAL is how often the measurement is made. This corresponds to **DataInterval()** of the GOES data table or the scan interval if **DataInterval()** is not used.
- DATA is the data that is stored in the GOES table.
- APPENDED OPTIONS refers to data that can be appended to the transmission.
- SHEF Codes can be added as headers or at the beginning of lines using GOESField() option SHEF.
- Value has a fixed width (Table B-2 [p. 46]).
- Value has a fixed precision (Table B-2 [p. 46]).
- Value only has a leading sign when negative (-).
- Data outside of operating range will be set to the minimum or maximum of the range.

Format of data transmitted:

- : <LABEL1> <OFFSET> #<INTERVAL> <DATA1> <CATA1> ... <DATA1>>
- : <LABEL2> <OFFSET> #<INTERVAL> <DATA2> <CATA2> ... <DATA2> ...

: <LABEL(N)> <OFFSET> #<INTERVAL> <DATA(N)> <DATA(N)> ... <DATA(N)>

Example output with explanation:

```
GoesTable() Fields_Scan_Order = TRUE, Newest_First=FALSE, Format = 6
GoesField() Decimation = 4, Precision = 3, Width = 5, SHEF set to VB and TA
(see Table B-3 [p. 51])
        <CR><LF><SPC>:VB<SPC>8<SPC>#15<SPC>13.15<SPC>13.13<SPC>13.18<SPC>13.19
        <CR><LF><SPC>:TA<SPC>8<SPC>#15<SPC>26.76<SPC>26.76<SPC>26.85<SPC>26.98<CR><LF>
```

Table B-3: Example SHEF output with descriptions									
Output	Description								
:VB	SHEF Code VB (Voltage – Battery)								
8	Reading is 8 minutes old (happened 8 minutes prior to transmission)								
#15	15-minutes measurement interval								
13.15	Most recent sensor or measurement reading								
13.13	Sensor or measurement reading taken 15 minutes prior to transmission								
13.18	Sensor or measurement reading taken 30 minutes prior to transmission								
13.19	Sensor or measurement reading taken 45 minutes prior to transmission								
:TA	SHEF Code TA (Temperature, air, dry bulb)								
8	Reading is 8 minutes old (happened 8 minutes prior to transmission)								
#15	15-minutes measurement interval								
26.76	Most recent sensor or measurement reading								
26.76	Sensor or measurement reading taken 15 minutes prior to transmission								
26.85	Sensor or measurement reading taken 30 minutes prior to transmission								
26.98	Sensor or measurement reading taken 45 minutes prior to transmission								

B.2 Pseudobinary data formats

The pseudobinary data format is a modified-ASCII format that uses the lower 6 bits of each 8-bit data character to represent part of a binary message. To encode a number, its binary form is broken into groups of 6 bits. Each group is placed into the lower 6 bits of a respective byte. The

number 64 is added to each byte to set the seventh bit. Binary numbers are transmitted MSB (most significant bit) first.

Pseudobinary formats are preferred for GOES and Meteosat/EUMETSAT self-timed transmissions because users can include more data in the GOES message. This allows more data to be transmitted in a specific window of transmission time.

NOTE:

These messages are not human readable and need to be decoded by computer software or by using custom decoding tables.

Because only 6 bits are used in each byte, the range that a byte or series of bytes can represent is diminished (Table B-4 [p. 52]).

Table B-4: Pseudobinary ranges								
Pseudobinary type	Range							
1-byte encoded unsigned integer	0 to +63							
1-byte encoded signed integer	-32 to +31							
2-byte encoded unsigned integer	0 to +4094							
2-byte encoded signed integer	-2048 to +2047							
3-byte encoded unsigned integer	0 to +262143							
3-byte encoded signed integer	-131072 to +131071							
4-byte encoded unsigned integer	0 to +16777215							
4-byte encoded signed integer	-8388608 to +8388607							

B.2.1 Campbell Scientific FP2 data

The FP2 data format uses 16 bits to represent a variable-precision floating point number. FP2 has a total range of -7999 to 7999 and variable precision of 0.001 to 1. It also has the ability to signal +/– INF and NAN, most commonly used to indicate a computational or measurement error. Table B-5 (p. 53) shows the numeric ranges and precision; Table B-6 (p. 53) describes the bits, and Table B-7 (p. 53) provides bit usage in calculating a finished value.

Table B-5: FP2 range and maximum precision										
Range	Maximum precision	b15 and b14 bit pattern								
-7.999 to 7.999	0.001	11								
-79.99 to 79.99	0.01	10								
-799.9 to 799.9	0.1	01								
-7,999 to 7,999	1	00								

Table B-6: Bit description									
Name	Bit	Description							
		Specifies the sign of the value.							
sign (s)	IQ (IVI2B)	0 = positive, 1 = negative.							
Exponent (E)	15 and 14	Specifies the magnitude of the negative decimal exponent.							
Mantissa (M)	13 to 0 (LSB)	Specifies the magnitude of the 13-bit mantissa, 0 to 8191							

Table B-7: Calculation of finished value											
Sign (S)	Exponent (E)	Mantissa (M)	FP2 value equals								
0	00	8191	+ INF								
1	00	8191	– INF								
1	00	8190	NAN								
0 or 1	00 or 01 or 10	0 to 7999	(-1 ^ S) × (10 ^ -E) × M								

When transmitted in a pseudobinary format, the 16 bits are encoded as follows. Bits 16 through 13 are the least significant four bits of the first byte, bits 12 through 7 are the least significant six bits of the second byte, and the last six bits are the least significant bits of the last byte. The following tables are examples of encoding values.

Table B-8: Encoding of 1234

5																							
Character 1 = @								Character 2 = S							Character 3 = R								
				Sign	Exponent Mantissa				Mantissa					Mantissa						Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	0	0	0	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Та	ble	B-9	9: E	ncod	ing o	f 1.23	34																
			Cł	narac	ter 1	= F				Ch	arac	ter 2	= S					Ch	arac	ter 3	3 = F	8	
				Sign	Expc	onent	Mantissa					Mant	issa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	0	1	1	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Та	ble	B-1	10:	Encod	ding	of 12.	34																
			Cł	naract	ter 1 =	= D				Ch	arac	ter 2	= S					Cha	arac	ter 3	3 = F	R	
	Character I = D Character 2 = S Character 3 = R Sign Exponent Mantissa Mantissa																						
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	0	1	0	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Та	ble	B-1	11: E	Incoc	ling o	of 123	3.4																
			Cł	naract	ter 1 :	= B				Ch	arac	ter 2	= S					Cha	arac	ter 3	3 = F	R	
				Sign	Expc	onent	Mantissa					Manti	issa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	0	0	1	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Table B-12: Encoding of 0.123

					5																		
	Character 1 = F									Ch	arac	ter 2	= A					Ch	arac	ter	3 = {		
				Sign	Expc	onent	Mantissa					Mant	issa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	0	1	1	0	0	1	0	0	0	0	0	1	0	1	1	1	1	0	1	1

Та	ble	B-1	13:	Encod	ding	of -12	234																
			Cł	naract	:er 1 =	= H				Ch	arac	ter 2	= S					Ch	arac	ter 3	3 = F	8	
	Character 1 = H Character 2 = S Character 3 = R Sign Exponent Mantissa Mantissa Mantissa																						
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	1	0	0	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Та	ble	B-1	14:	Enco	ding	of -1.	234																
	Character 1 = N Character 2 = S Character 3 = R Sign Exponent Maptisca Maptisca																						
	Character 1 = N Character 2 = S Character 3 = R Sign Exponent Mantissa Mantissa Mantissa																						
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	1	1	1	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Та	ble	B-1	15:	Encod	ding	of -12	2.34																
			Cł	narac	ter 1	= L				Ch	arac	ter 2	= S					Cha	arac	ter 3	3 = F	8	
				Sign	Expc	onent	Mantissa					Mant	ssa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	1	1	0	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Table B-16: Encoding of -123.4

			C	harac	ter 1	= J				Ch	arac	ter 2	: = S					Ch	arac	ter 3	3 = F	8	
				Sign	Expc	onent	Mantissa					Mant	issa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	1	0	1	0	0	1	0	1	0	0	1	1	0	1	0	1	0	0	1	0

Table B-17: Encoding of -0.123

			Cł	naract	:er 1 =	= N				Ch	arac	ter 2	= A					Ch	arac	cter	3 = {	[
				Sign	Expo	nent	Mantissa					Mant	issa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	1	1	1	0	0	1	0	0	0	0	0	1	0	1	1	1	1	0	1	1

Та	ble	B-1	18:	Encod	ding	of IN	F																
			Cł	naract	ter 1 =	= A				Ch	arac	ter 2	= ?					Ch	arac	ter 3	3 = ?)	
				Sign	Expo	onent	Mantissa					Manti	ssa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	0	0	0	1	0	0	1	1	1	1	1	1	0	0	1	1	1	1	1	1

Та	ble	B-1	19:	Encod	ding	of -IN	IF																
			C	harac	ter 1	=				Ch	arac	ter 2	! = ?					Ch	arac	ter 3	3 = ?)	
				Sign	Expc	onent	Mantissa					Mant	issa							Man	tissa		
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	1	0	0	1	0	0	1	1	1	1	1	1	0	0	1	1	1	1	1	1

Та	ble	B-2	20:	Enco	ding	of N/	٩N																
			C	harac	ter 1	=				Ch	arac	ter 2	= ?					Cha	arac	ter 3	8 = ~	,	
	Character 1 = I Character 2 = ? Character 3 = ~ Sign Exponent Mantissa Mantissa Mantissa																						
р	1	0	0	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	1	0	0	1	0	0	1	1	1	1	1	1	0	0	1	1	1	1	1	0

B.2.2 Pseudobinary

Pseudobinary or 18-bit integer data format is used to transmit a signed or unsigned integer. The 18 bits are encoded across 3 bytes. When signed, the value is encoded using a two-complement representation. As an integer cannot directly represent a fractional number, measurements are often scaled before storing to the GOES data table. For example, a water-level surface elevation of 123.45 ft can be multiplied by 100 to get an integer of 12345. This integer is stored for transmission with the encoding shown in Table B-21 (p. 57).

Tab	Fable B-21: Example encoding of water level surface elevation value of 12345																						
	Character 1 = C							Character 2 = @								Character 3 = y							
р	1	b18	b17	b16	b15	b14	b13	р	1	b12	b11	b10	b9	b8	b7	р	1	b6	b5	b4	b3	b2	b1
0	1	0	0	0	0	1	1	0	1	0	0	0	0	0	0	0	1	1	1	1	0	0	1

B.2.3 Additional pseudobinary representations

Other pseudobinary representations, such as 6, 12, and 24 bit integers, can be formed and transmitted using CRBasic.

B.3 Transmission durations

Table B-22 (p. 58) provides the transmission durations, calculated from the number of bytes in a message. Table B-23 (p. 58) provides the maximum data bytes for an assigned time slot duration. Users need to convert the data points they want to send to number of bytes.

Table B-22: Calculating transmission duration for GOES 300/1200 bps messages							
Transmit type	Transmission duration (seconds) (where N = number of data bytes in a message)						
Self-timed, 300 bps	(137 + (N × 4))/150						
Random, 300 bps	(137 + (N × 4))/150						
Self-timed, 1200 bps	(223 + (N × 4))/600						
Random, 1200 bps	(223 + (N × 4))/600						

Table B-23: GOES self-timed-message maximum data bytes and assigned time-slot duration										
Assigned time-slot duration (seconds)	GOES 300 bps maximum data per message (bytes)	GOES 1200 bps maximum data per message (bytes)								
5	153	694								
10	340	1444								
15	528	2194								
20	715	2944								
25	903	3694								
30	1090	4444								
35	1278	5194								
40	1465	5944								
45	1653	6694								
50	1840	7444								
55	2028	8194								
60	2215	8944								

Appendix C. GOES Version 2 DCS channel frequencies

The following tables provide the frequencies for each channel.

Table C-1: GOES V 2.0 DCS frequencies for channels 1 through 46 and 301 through 346 ¹												
Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)					
1	401.701000	312	401.718250	24	401.735500	335	401.752750					
301	401.701750	13	401.719000	324	401.736250	36	401.753500					
2	401.702500	313	401.719750	25	401.737000	336	401.754250					
302	401.703250	14	401.720500	325	401.737750	37	401.755000					
3	401.704000	314	401.721250	26	401.738500	337	401.755750					
303	401.704750	15	401.722000	326	401.739250	38	401.756500					
4	4 401.705500 315 401.722750 27 401.740000 338 401.757250											
304	401.706250	16	401.723500	327	401.740750	39	401.758000					
5	401.707000	316	401.724250	28	401.741500	339	401.758750					
305	401.707750	17	401.725000	328	401.742250	40	401.759500					
6	401.708500	317	401.725750	29	401.743000	340	401.760250					
306	401.709250	18	401.726500	329	401.743750	41	401.761000					
7	401.710000	318	401.727250	30	401.744500	341	401.761750					
307	401.710750	19	401.728000	330	401.745250	42	401.762500					
8	401.711500	319	401.728750	31	401.746000	342	401.763250					
308	401.712250	20	401.729500	331	401.746750	43	401.764000					
9	401.713000	320	401.730250	32	401.747500	343	401.764750					
309	401.713750	21	401.731000	332	401.748250	44	401.765500					
10	401.714500	321	401.731750	33	401.749000	344	401.766250					
310	401.715250	22	401.732500	333	401.749750	45	401.767000					
11	401.716000	322	401.733250	34	401.750500	345	401.767750					
311	401.716750	23	401.734000	334	401.751250	46	401.768500					
12	12 401.717500 323 401.734750 35 401.752000 346 401.769250											
¹ Bold text i	ndicates possible 12	200 bps cha	nnel assignments.									

Table C-2: GOES V 2.0 DCS frequencies for channels 47 through 108 and 347 through 408 ¹											
Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)				
47	401.770000	362	401.793250	78	401.816500	393	401.839750				
347	401.770750	63	401.794000	378	401.817250	94	401.840500				
48	401.771500	363	401.794750	79	401.818000	394	401.841250				
348	401.772250	64	401.795500	379	401.818750	95	401.842000				
49	401.773000	364	401.796250	80	401.819500	395	401.842750				
349	401.773750	65	401.797000	380	401.820250	96	401.843500				
50	401.774500	365	401.797750	81	401.821000	396	401.844250				
350	401.775250	66	401.798500	381	401.821750	97	401.845000				
51	401.776000	366	401.799250	82	401.822500	397	401.845750				
351	401.776750	67	401.800000	382	401.823250	98	401.846500				
52	401.777500	367	401.800750	83	401.824000	398	401.847250				
352	401.778250	68	401.801500	383	401.824750	99	401.848000				
53	401.779000	368	401.802250	84	401.825500	399	401.848750				
353	401.779750	69	401.803000	384	401.826250	100	401.849500				
54	401.780500	369	401.803750	85	401.827000	400	401.850250				
354	401.781250	70	401.804500	385	401.827750	101	401.851000				
55	401.782000	370	401.805250	86	401.828500	401	401.851750				
355	401.782750	71	401.806000	386	401.829250	102	401.852500				
56	401.783500	371	401.806750	87	401.830000	402	401.853250				
356	401.784250	72	401.807500	387	401.830750	103	401.854000				
57	401.785000	372	401.808250	88	401.831500	403	401.854750				
357	401.785750	73	401.809000	388	401.832250	104	401.855500				
58	401.786500	373	401.809750	89	401.833000	404	401.856250				
358	401.787250	74	401.810500	389	401.833750	105	401.857000				
59	401.788000	374	401.811250	90	401.834500	405	401.857750				
359	401.788750	75	401.812000	390	401.835250	106	401.858500				
60	401.789500	375	401.812750	91	401.836000	406	401.859250				
360	401.790250	76	401.813500	391	401.836750	107	401.860000				
61	401.791000	376	401.814250	92	401.837500	407	401.860750				
361	401.791750	77	401.815000	392	401.838250	108	401.861500				
62	401.792500	377	401.815750	93	401.839000	408	401.862250				
¹ Bold text in	ndicates possible	1200 bps cha	annel assignment	S.							

Table C-3: GOES V 2.0 DCS frequencies for channels 109 through 170 and 409 through 470 ¹											
Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)				
109	401.863000	424	401.886250	140	401.909500	455	401.932750				
409	401.863750	125	401.887000	440	401.910250	156	401.933500				
110	401.864500	425	401.887750	141	401.911000	456	401.934250				
410	401.865250	126	401.888500	441	401.911750	157	401.935000				
111	401.866000	426	401.889250	142	401.912500	457	401.935750				
411	401.866750	127	401.890000	442	401.913250	158	401.936500				
112	401.867500	427	401.890750	143	401.914000	458	401.937250				
412	401.868250	128	401.891500	443	401.914750	159	401.938000				
113	401.869000	428	401.892250	144	401.915500	459	401.938750				
413	401.869750	129	401.893000	444	401.916250	160	401.939500				
114	401.870500	429	401.893750	145	401.917000	460	401.940250				
414	401.871250	130	401.894500	445	401.917750	161	401.941000				
115	401.872000	430	401.895250	146	401.918500	461	401.941750				
415	401.872750	131	401.896000	446	401.919250	162	401.942500				
116	401.873500	431	401.896750	147	401.920000	462	401.943250				
416	401.874250	132	401.897500	447	401.920750	163	401.944000				
117	401.875000	432	401.898250	148	401.921500	463	401.944750				
417	401.875750	133	401.899000	448	401.922250	164	401.945500				
118	401.876500	433	401.899750	149	401.923000	464	401.946250				
418	401.877250	134	401.900500	449	401.923750	165	401.947000				
119	401.878000	434	401.901250	150	401.924500	465	401.947750				
419	401.878750	135	401.902000	450	401.925250	166	401.948500				
120	401.879500	435	401.902750	151	401.926000	466	401.949250				
420	401.880250	136	401.903500	451	401.926750	167	401.950000				
121	401.881000	436	401.904250	152	401.927500	467	401.950750				
421	401.881750	137	401.905000	452	401.928250	168	401.951500				
122	401.882500	437	401.905750	153	401.929000	468	401.952250				
422	401.883250	138	401.906500	453	401.929750	169	401.953000				
123	401.884000	438	401.907250	154	401.930500	469	401.953750				

Table C-3	Table C-3: GOES V 2.0 DCS frequencies for channels 109 through 170 and 409 through 470 ¹											
Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)					
423	401.884750	139	401.908000	454	401.931250	170	401.954500					
124	124 401.885500 439 401.908750 155 401.932000 470 401.955250											
¹ Bold text indicates possible 1200 bps channel assignments.												

Table C-4: GOES V 2.0 DCS frequencies for channels 171 through 230 and 471 through 530 ¹											
Channel	Frequency	Channel	Frequency	Channel	Frequency	Channel	Frequency				
number	(MHz)	number	(MHz)	number	(MHz)	number	(MHz)				
171	401.956000	186	401.978500	201	402.001000	216	402.023500				
471	401.956750	486	401.979250	501	402.001750	516	402.024250				
172	401.957500	187	401.980000	202	402.002500	217	402.025000				
472	401.958250	487	401.980750	502	402.003250	517	402.025750				
173	401.959000	188	401.981500	203	402.004000	218	402.026500				
473	401.959750	488	401.982250	503	402.004750	518	402.027250				
174	401.960500	189	401.983000	204	402.005500	219	402.028000				
474	401.961250	489	401.983750	504	402.006250	519	402.028750				
175	401.962000	190	401.984500	205	402.007000	220	402.029500				
475	401.962750	490	401.985250	505	402.007750	520	402.030250				
176	401.963500	191	401.986000	206	402.008500	221	402.031000				
476	401.964250	491	401.986750	506	402.009250	521	402.031750				
177	401.965000	192	401.987500	207	402.010000	222	402.032500				
477	401.965750	492	401.988250	507	402.010750	522	402.033250				
178	401.966500	193	401.989000	208	402.011500	223	402.034000				
478	401.967250	493	401.989750	508	402.012250	523	402.034750				
179	401.968000	194	401.990500	209	402.013000	224	402.035500				
479	401.968750	494	401.991250	509	402.013750	524	402.036250				
180	401.969500	195	401.992000	210	402.014500	225	402.037000				
480	401.970250	495	401.992750	510	402.015250	525	402.037750				
181	401.971000	196	401.993500	211	402.016000	226	402.038500				
481	401.971750	496	401.994250	511	402.016750	526	402.039250				
182	401.972500	197	401.995000	212	402.017500	227	402.040000				
482	401.973250	497	401.995750	512	402.018250	527	402.040750				
183	401.974000	198	401.996500	213	402.019000	228	402.041500				
483	401.974750	498	401.997250	513	402.019750	528	402.042250				
184	401.975500	199	401.998000	214	402.020500	229	402.043000				
484	401.976250	499	401.998750	514	402.021250	529	402.043750				
185	401.977000	200	401.999500	215	402.022000	230	402.044500				
485	401.977750	500	402.000250	515	402.022750	530	402.045250				
¹ Bold text in	ndicates possible	1200 bps ch	annel assignmen	ts.							

Table C-5: GOES V 2.0 DCS frequencies for channels 231 through 266 and 531 through 566 ¹													
Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)	Channel number	Frequency (MHz)						
231	402.046000	240	402.059500	249	402.073000	258	402.086500						
531	402.046750	540	402.060250	549	402.073750	558	402.087250						
232	402.047500	241	402.061000	250	402.074500	259	402.088000						
532	402.048250	541	402.061750	550	402.075250	559	402.088750						
233	233 402.049000 242 402.062500 251 402.076000 260 402.089500												
533	402.049750	542	402.063250	551	402.076750	560	402.090250						
234	402.050500	243	402.064000	252	402.077500	261	402.091000						
534	402.051250	543	402.064750	552	402.078250	561	402.091750						
235	402.052000	244	402.065500	253	402.079000	262	402.092500						
535	402.052750	544	402.066250	553	402.079750	562	402.093250						
236	402.053500	245	402.067000	254	402.080500	263	402.094000						
536	402.054250	545	402.067750	554	402.081250	563	402.094750						
237	402.055000	246	402.068500	255	402.082000	264	402.095500						
537	402.055750	546	402.069250	555	402.082750	564	402.096250						
238	402.056500	247	402.070000	256	402.083500	265	402.097000						
538	402.057250	547	402.070750	556	402.084250	565	402.097750						
239	402.058000	248	402.071500	257	402.085000	266	402.098500						
539	402.058750	548	402.072250	557	402.085750	566	402.099250						
¹ Bold text i	ndicates possible	1200 bps ch	annel assignments	i.									

Appendix D. Watch test results

The following is a full set of test results from a watch test showing the communications between the TX325 and a data logger:

12:15:00.050	Т	01	00	14	14	04								
12:15:00.066	R	01	0A	14	00	00	20	00	10					
12:15:00.076	R	13	0F	00	23	FE	71	04						
12:15:00.096	Т	01	00	1F	1F	04								.#.q.
12:15:00.106	R	01	02	F0										
12:15:00.116	R	23	FB	F6	04									#
12:15:00.136	Т	01	00	10	00	10	04						•	
12:15:00.146	R	01	06											• •
12:15:00.186	Т	01	00	1D	1D	04								
12:15:00.196	R	01	7A	1D										.z.
12:15:00.206	R	00	20	20	20	20	20	20	20					•
12:15:00.216	R	20	31	2E	36	20	20	20	20					1.6
12:15:00.226	R	20	31	35	3A	32	32	3A	32				15	:22:2
12:15:00.236	R	36	20	20	20	20	20	20	20					6
12:15:00.246	R	20	30	31	2F	31	37	2F	32				01,	/17/2
12:15:00.256	R	30	31	38	20	20	20	20	20					018
12:15:00.266	R	20	4F	6D	6E	69	53	61	74				Omi	niSat
12:15:00.276	R	2D	33	00	20	20	20	20	20					-3.
12:15:00.286	R	20	20	20	20	20	20	20	20					
12:15:00.296	R	20	20	20	20	20	20	20	20					
12:15:00.306	R	20	20	20	20	20	20	20	20					
12:15:00.316	R	20	20	20	20	20	20	20	20					
12:15:00.326	R	20	20	20	20	20	20	20	20					
12:15:00.336	R	20	20	20	20	20	20	20	20					
12:15:00.346	R	20	20	20	20	20	20	20	20					
12:15:00.356	R	20	FF	04										
12:15:00.376	Т	01	00	10	00	10	04						•	
12:15:00.386	R	01	06											
12:15:00.396	R	10	00	23	FE	23	FB	D2	F0				#	.#
12:15:00.406	R	DD	04											
12:15:00.426	Т	01	00	74	00	00	00	00	5E	D2 0	4		t	^
12:15:00.466	R	01	60	74	00									.`t.
12:15:00.476	R	35	2F	14	35	11	14	34	98				5/.	54.
12:15:00.486	R	34	31	34	35	2E	39	34	31				414	5.941
12:15:00.496	R	37	30	4E	31	31	31	35	31				70N	11151
12:15:00.506	R	2E	32	38	32	38	30	57	31				.282	280W1
12:15:00.516	R	34	32	31	2E	33	20	00	10				421	.3
12:15:00.526	R	12	29	1D	00	00	00	00	00				.).	
12:15:00.536	R	00	00	00	00	00	00	00	0B					
12:15:00.546	R	7C	23	FE	FF	60	15	23	FE				#.	.`.#.
12:15:00.556	R	FF	80	12	00	43	00	43	23					.C.C#

12:15:00.566	R	FB	02	23	FE	00	00	00	23									##
12:15:00.576	R	FE	DF	00	00	20	00	10	13									
12:15:00.586	R	0A	0A	00	00	C3	23	FE	00									#
12:15:00.596	R	4C	20	00	00	76	04											Lv.
12:15:07.053	Т	01	00	1F	1F	04												
12:15:07.063	R	01	02	F0														
12:15:07.073	R	23	FB	F6	04													#
12:15:07.093	Т	01	00	14	14	04												
12:15:07.103	R	01	0A	14														
12:15:07.113	R	00	00	20	00	10	13	0F	07									
12:15:07.123	R	02	79	04														.у.
12:15:07.220	Т	01	00	10	00	10	04											
12:15:07.240	R	10	00	23	FE	23	FB	D2	F0									#.#
12:15:07.250	R	DD	04															
12:15:07.270	Т	01	00	1E	00	00	20	00	10	13	0F	0A	00	4E	55	4C	4C	NULL
12:15:07.270	Т	2E	44	41	54	00	00	00	00	00	00	00	00	00	00	C3	00	.DAT
12:15:07.270	Т	4C	23	FE	00	00	00	00	00	00	00	00	00	00	00	00	00	L#
12:15:07.270	Т	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	00	
12:15:07.270	Т	00	0D	0A	31	33	2E	36	31	33	2C	31	33	2E	36	31	34	13.613,13.614
12:15:07.270	Т	2C	31	33	2E	36	31	33	2C	31	33	2E	36	31	33	2C	31	,13.613,13.613,1
12:15:07.270	Т	33	2E	36	31	37	2C	0D	0A	32	34	2E	37	31	37	2C	32	3.617,24.717,2
12:15:07.270	Т	34	2E	36	39	31	2C	32	34	2E	36	36	36	2C	32	34	2E	4.691,24.666,24
12:15:07.270	Т	36	34	33	2C	32	34	2E	36	32	32	2C	0D	0A	A6	04		643,24.622,
12:15:07.430	R	01	02	1E	00	20	04											

Appendix E. Antenna gain for nonstandard antennas

GOES Antenna Gain is for specifying a different value if using an antenna other than the standard Yagi 11 dBi antenna. For standard GOES setups that use the 11 dB directional antenna specified for the system, the default value of 100 will be adequate for your setup.

If your GOES data logger program is based on the example programs, this value should be adjusted in code.

An alternative to adjusting the value in code is to do it in the constants table. Be aware that while this approach is easy, it may not always work well for tracking the current setting held in the data logger and its program. Adjusting the constants can be done from the **Terminal mode** of the data logger using the following procedure:

- 1. Connect to the data logger using *Device Configuration Utility*.
- 2. Click the Terminal tab.
- 3. Click in the window and press **Enter** until you see the **CR1000X>** prompt.
- 4. Type capital **C** and press **Enter**.
- 5. Specify the number on the left corresponding to the **Constant Value** you want to change and press Enter.

6. Type the value for the constant you would like to change and press Enter.

O DevConfig 2.29	- 🗆 X
File Language Backup Options	s Help
Device Type	Deployment 🎒 Security Check Logger Control Data Monitor Data Collection File Control Manage OS Settings Editor Termina
Q NL201	
Favorites	CR1000X>C
CR1000	
CR 1000X Series	Constant Table:
CR 300 Series	1)GENERAL_OPTIONS = == GENERAL OPTIONS ==
CP 350 Series	2) GOES_ENABLE = 1
CR6 Series	3) GOES_COMPORT = 1
CRO Series	4) GOES RADIO_TYPE = 3
CR800 Series	5) GOES_ID = 12345678
NL200 Series	6) OIC_PERST - 23200
RF450) SELF_IMED_CHANNEL = 0
RF451/452	9) SEL TIME BAID RATE = 300
Unknown	10) SELF TIMED INTERVAL = 00:00:03:00
	11) SELF TIMED OFFSET = 00:20:00
	12) SELF TIMED WINDOW = 10
	13) SELF_TIMED_IX_ANTENNA_GAIN = 140
	14)RANDOM_OPTIONS = == RANDOM OPTIONS ==
	15) RANDOM_CHANNEL = 0
	16) RANDOM_BAUD_RATE = 300
	17) RANDOM_INTERVAL = 00:30:00
	18) RANDOM_REPEAT_COUNT = 1
Connection Type	19) RANDOM_TX_ANTENNA_GAIN = 140
Direct IP	20) DATA OPTIONS = = DATA OPTIONS ==
	21) DATA FORMAT = 3
Communication Port	22) NUMBER_OF_ALUES_IO_IX = 4
COM3	23) _APPLI_CRANGES APPLI SELIINGS
	SELECTIMED TX ANTENNA GAIN = 140
PakBus Encryption Key (j)	Enter New Value for SELF TIMED TX ANTENNA GAIN:
Baud Rate	
115200 ~	
Specify PakBus Address	
Disconnect	All Caps Echo Input Pause Clear Start Export Senc File
Disconnect	
Appendix F. TX321 program converted to TX325 program (CR1000, CR3000, CR800-series)

CAUTION:

Use the latest operating system for your data logger, 32.06 or later. Do not run a program that changes the Platform ID repetitively. Doing so can lead to failure of the EEPROM from excessive write cycles. If your program must use different Platform IDs at different times, the newer data loggers (CR6, CR300 series, CR350 series, CR1000X) support this.

This appendix discusses modifying a program for a CR3000, CR1000, or CR800-series data logger to use a TX325 instead of a TX321. It also discusses the TX325 features and commands that are not supported in the older data loggers and the interfaces required to connect the TX325 to an older data logger.

Some TX325 features and commands are not supported in the older data logger operating system (OS) because of memory size limitations of older data loggers.

The TX321 had a CS I/O interface, so the commands (GOESData) output data to the CS I/O port. The TX325 only has an RS-232 port, so the new commands that were added use the RS-232 interface on the data logger. This means that it will not be possible to connect to the RS-232 with *LoggerNet*, and another interface will need to be used for that. Campbell Scientific recommends using an SC32B, and connect the computer RS-232 (or USB to RS-232 adapter) to the SC32B and to the data logger CS I/O. Additionally, if the data logger has an Ethernet interface, the data logger may use an IP link to connect to the computer. An RS-232 interface is require If the data logger OS need to be updated.

The TX325 uses different CRBasic commands from the TX321. Often, the commands are similar, but not all functions are available. It is highly recommended to download the example program available at www.campbellsci.com/downloads/tx325-example-program-cr3000-cr1000-cr800 2. This appendix provides the changes that need to be made to a data logger program that allows it to use a TX325 instead of the TX321. It is important to copy/paste or work from the online example, only using this appendix as a guide.

When using a TX321, the configuration parameters for the GOES radio may have been set either using the *Device Configuration Utility* software, or by using the GOESSetup() CRBasic

instruction. A *Device Configuration* page is not available for the TX325 when it is connected to an older data logger. With an older data logger, the configuration parameters for the GOES radio must be set programmatically using the EnviroSatRandomSetup and EnviroSatSTSetup commands. The following are the three methods available for adding it to a program:

- 1. The EnviroSatRandomSetup and EnviroSatSTSetup commands can be coded with the arguments directly in the program, which is convenient when the user has only one station.
- 2. The configuration settings can be listed in a ConstTable, which allows them to be configured by changing the site specific settings from a template file that is used at multiple sites. Once the Boolean ApplyAndRestart is set to true, those changed constants will be applied and the program recompiled. If an archived copy of the program is kept that is running (and we recommend that you do), you will need to download it using File Control or do a Backup Datalogger (using the Device Configuration Utility software) and save it so that you know which site it applies to.
- 3. A file can declare and define the configuration variables and can include the measurement algorithms. The advantage to this is that as the measurements evolve, the same template file can more likely be used at multiple sites, since it does not include site specific parameters. If the program attempts to be compiled without finding the file, the compile will fail, since the variables used in the EnviroSatRandomSetup and EnviroSatSTSetup commands won't be found.

The following is an example of an include file named **IncludeFile.CR1**. It can have any suffix such as .CR8 or .text. It will simply require changing the filter in the file selector for the file to **Send in File Control**.

```
'GOES configuration settings for MySite
Const dcp_platform_id As Long = &h01234567
Const rt_baud_rate = 300
Const rt_channel = 195
Const rt_count = 2 'we can only send two messages max in a 2 minute RT interval.
'We can send more if our RT interval is larger.
Const rt_interval As String = "00_02_00"
Const st_baud_rate = 300
Const st_channel = 195
Const st_interval As String = "00_01_00_00"
Const st_message_window_size As Long = 10
```

Const st_offset As String = "00_45_50"

Use File Control to send it to the CPU drive. Uncheck Run Now and Run On Power-up, as it will not compile.

	IncludeFile.CR1	
Run Now		
O Preserve	e data if no table changed	
O Delete a	ssociated data tables created by:	
Run On Po	wer-up	

In the main file, add the following line before the **BeginProg** command:

Include "CPU:IncludeFile.CR1"

Send the main file. It should pull in IncludeFile.CR1 and compile without error.

The TX325 status is sent as an array of 37 values. Allocate and set aliases as follows or similarly:

```
Public tx_325_status(37) As Long
 Alias tx_325_status(1) = status_result
  '0 = success, -1 = timout, -2 = no SOH character returned, -3 = bad checksum
 '-10 = no CTS asserted
Public tx_325_status_results As String * 30
 Alias tx_325_status(2) = time_status
  '&h00 = completed OK, &h0A = time-of-day clock not loaded yet.
Public tx_325_time_status As String * 50
 Alias tx_325_status(3) = reported_year 'current year.
 Alias tx_325_status(4) = julian_day 'current day into the year
Public reported_month As Long
Public reported_day As Long
 Alias tx_325_status(5) = reported_hour
 Alias tx_325_status(6) = reported_minute
 Alias tx_325_status(7) = reported_second
 Alias tx_325_status(8) = reported_tenths_of_a_second
 Alias tx_325_status(9) = reported_radio_id_decimal
 Alias tx_325_status(10) = radio_firmware_build_time
 Alias tx_325_status(11) = radio_firmware_build_date
 Alias tx_325_status(12) = radio_battery_voltage
 Alias tx_325_status(13) = radio_temperature
 Alias tx_325_status(14) = radio_battery_voltage_before_last_tx
 Alias tx_325_status(15) = radio_temperature_before_last_tx
 Alias tx_325_status(16) = radio_battery_during_last_tx
 Alias tx_325_status(17) = latitude_deg
 Alias tx_325_status(18) = latitude_min
 Alias tx_325_status(19) = latitude_direction
 Alias tx_325_status(20) = longitude_deg
 Alias tx_325_status(21) = longitude_min
 Alias tx_325_status(22) = longitude_direction
 Alias tx_325_status(23) = altitude 'reported in meters
```

```
Alias tx_325_status(24) = year_of_last_gps_fix

Alias tx_325_status(25) = julian_day_of_last_gps_fix

Alias tx_325_status(26) = hour_of_last_gps_fix

Alias tx_325_status(27) = minute_of_last_gps_fix

Alias tx_325_status(28) = second_of_last_gps_fix

Alias tx_325_status(29) = number_of_missed_gps_fix_attempt

Alias tx_325_status(30) = year_of_last_missed_gps_fix_attempt

Alias tx_325_status(31) = julian_day_of_last_missed_gps_fix_att

Alias tx_325_status(32) = hour_of_last_missed_gps_fix_attempt

Alias tx_325_status(33) = minute_of_last_missed_gps_fix_attempt

Alias tx_325_status(34) = second_of_last_missed_gps_fix_attempt

Alias tx_325_status(35) = radio_gps_health

Alias tx_325_status(36) = radio_failsafe_status

Alias tx_325_status(37) = duration_of_last_radio_transmission
```

Commands used with the TX321 were named similar to GOESStatus (GOES_RCode1(1), 2) The similar, but not equivalent, command that has been added to operating systems for the older data loggers is: EnviroSatStatus(tx_325_status).

NOTE:

Return values and their meanings may differ or be in different units or formats.

Code similar to the following may be appropriate for retrieving status and interpreting it:

Sub GetTX325_StatusAndProcess 'This section of CRBasic code polls the TX325 radio and 'converts some diagnostic data into human readable values.

```
EnviroSatStatus(tx_325_status)
 If (status_result = 0) Then
   tx_325_status_results = "Success."
   ElseIf (status_result = -1) Then
    tx_325_status_results = "Timed Out."
   ElseIf (status_result = -2) Then
    tx_325_status_results = "No SOH character returned."
   ElseIf (status_result = -3) Then
    tx_325_status_results = "Bad Checksum."
   ElseIf (status_result = -10) Then
    tx_325_status_results = "No CTS Asserted."
 EndIf
 If (time_status = &h00) Then
   tx_325_time_status = "Completed OK."
 ElseIf (time_status = &hOA) Then
    tx_325_time_status = "Time-of-day clock not loaded yet."
 EndIf
'everything done from here is to help make things human readable
 If (status_result = 0) Then
   Sprintf (reported_radio_id_hex, "%08s", Hex (reported_radio_id_decimal))
   'ensures we always have 8 characters shown
     reported_latitude_direction_letter = CHR (latitude_direction)
```

```
reported_longitude_direction_letter = CHR (longitude_direction)
 Else
   reported_radio_id_hex = Hex ( 0 )
EndIf
If (status_result = 0) Then
 ConvertDayOfYear (julian_day, reported_year, reported_month, reported_day)
   current_tx325_time = reported_month & "/" & reported_day & "/" & _
   reported_year & " " & reported_hour & ":" & reported_minute & _
   ":" & reported_second & ":" & reported_tenths_of_a_second
 Else
   current_tx325_time = "1/0/1992 0:0:0:0"
EndIf
If (StrComp (current_tx325_time, "1/0/1992 0:0:0:0") = 0) Then
 current_tx325_time = "No 3D GPS fix yet or radio is offline!"
EndIf
If (status_result = 0) Then
 year_of_last_gps_fix = year_of_last_gps_fix + 1992
 ConvertDayOfYear (julian_day_of_last_gps_fix, year_of_last_gps_fix, _
 month_of_last_gps _fix,_ day_of_last_gps_fix)
 last_gps_fix_time = month_of_last_gps_fix & "/" & day_of_last_gps_fix & _
 "/" & year_of_last_gps_fix & " " & hour_of_last_gps_fix & ":" & _
 minute_of_last_gps_fix & ":" & second_of_last_gps_fix
Else
 last_qps_fix_time = "1/0/1992 0:0:0"
EndIf
If (StrComp (last_gps_fix_time, "1/0/1992 0:0:0") = 0) Then
 last_gps_fix_time = "No 3D GPS fix yet or radio is offline!"
EndIf
If (status_result = 0) Then
 year_of_last_missed_gps_fix_attempt = year_of_last_missed_gps_fix_attempt + 1992
 ConvertDayOfYear (julian_day_of_last_missed_gps_fix_att,year_of_last_missed_gps_fix_attempt, _
 month_of_last_missed_gps_attempt, day_of_last_missed_gps_attempt)
 last_missed_gps_fix_attempt = month_of_last_missed_gps_attempt & "/" & _
 day_of_last_missed_gps_attempt & "/" & year_of_last_missed_gps_fix_attempt _
 & " " & hour_of_last_missed_gps_fix_attempt & ":" & _
 minute_of_last_missed_gps_fix_attempt & ":" & _
 second_of_last_missed_gps_fix_attempt
Else
 last_missed_gps_fix_attempt = "1/0/1992 0:0:0"
EndIf
If ((StrComp (last_missed_gps_fix_attempt, "1/0/1992 0:0:0") = 0) _
```

```
AND (status_result = 0)) Then
   last_missed_gps_fix_attempt = "No misses so far!"
 Else
   last_missed_gps_fix_attempt = "Logger did not receive report from GOES radio."
 EndIf
If ((Hex (radio_gps_health) = &h00) AND (status_result = 0)) Then
qps_health = "Have valid GPS position fix."
 ElseIf (status_result <> 0) Then
 gps_health = "No fix, radio is offline!"
 ElseIf (Hex (radio_gps_health) = &h01) Then
 gps_health = "No fix, no GPS Satellites in view."
 ElseIf (Hex (radio_gps_health) = &h08) Then
 gps_health = "No fix, 0 usable GPS satellites in view."
 ElseIf (Hex (radio_gps_health) = &h09) Then
 gps_health = "No fix, 1 usable GPS satellites in view."
 ElseIf (Hex (radio_gps_health) = &hOA) Then
 gps_health = "No fix, 2 usable GPS satellites in view."
 ElseIf (Hex (radio_gps_health) = &hOB) Then
 gps_health = "No fix, 3 usable GPS satellites in view."
EndIf
If ((radio_failsafe_status = 0) AND (status_result = 0)) Then
failsafe_status = "TX325 is idle."
 ElseIf ((radio_failsafe_status = 1) AND (status_result = 0)) Then
 failsafe_status = "Transmit in progress."
 ElseIf ((radio_failsafe_status = 2) AND (status_result = 0)) Then
 failsafe_status = "Post-transmitfailsafe wait in progress."
 ElseIf (status_result <> 0) Then
 failsafe_status = "Logger did not receive report from GOES radio."
EndIf
'rt_tx_data_result_code = -99
If (st_tx_data_result_code = -99) Then
 self_timed_transmission_status = "Logger has not tried to send self-timed data."
 ElseIf (st_tx_data_result_code = 0) Then
 self_timed_transmission_status = "Successful EnviroSatData execution for self-timed."
 ElseIf (st_tx_data_result_code = -11) Then
 self_timed_transmission_status = "Buffer control error."
 ElseIf (st_tx_data_result_code = -16) Then
 self_timed_transmission_status = "Illegal data format sent to the TX325."
 ElseIf (st_tx_data_result_code = -17) Then
 self_timed_transmission_status = "Data format 0 or 1, but table not FP2 or ASCII."
 ElseIf (st_tx_data_result_code = -22) Then
 self_timed_transmission_status = "TX325 not setup correctly by logger."
EndIf
```

```
If (rt_tx_data_result_code = -99) Then
random_transmission_status = "Logger has not tried to send Random data."
ElseIf (rt_tx_data_result_code = 0) Then
random_transmission_status = "Successful EnviroSatData execution for Random."
ElseIf (rt_tx_data_result_code = -11) Then
random_transmission_status = "There was a buffer control error."
ElseIf (rt_tx_data_result_code = -16) Then
random_transmission_status = "Illegal data format was sent to the TX325."
ElseIf (rt_tx_data_result_code = -17) Then
random_transmission_status = "Data format 0 or 1, but table not FP2 or ASCII."
ElseIf (rt_tx_data_result_code = -22) Then
random_transmission_status = "TX325 was not setup correctly by the data logger."
EndIf
```

'convert millivolts to volts

current_radio_battery_voltage = radio_battery_voltage * .001
current_radio_battery_during_last_tx = radio_battery_during_last_tx * .001
current_battery_voltage_before_last_tx = radio_battery_voltage_before_last_tx * .001

If (status_result <> 0) Then Erase (tx_325_status())

EndSub

NOTE:

Because of priority and available memory, some status reports that were available on the TX321 may not be available from the commands implemented for the TX325 in the OS update for the older data loggers. These include (but may not be limited to): ForwardPower, ReflectPower, GPS_Acq_Time, and Osc_Drift.

When using the older data logger operating systems the status is only available as a response from the EnviroSatStatus command. Campbell Scientific recommends calling EnviroSatStatus when current information is needed. The following program exerts does this adding a trigger when the command is used to set the data logger clock:

```
' Run following commands everyday at 12 hours and 13 minutes.
If (Time_733m_24h OR set_clock_from_GPS) Then set_clock_from_GPS = False
```

```
' Obtain GPS time.
Call GetTX325_StatusAndProcess
' Ensure the GOES GPS command executed successfully
If (tx_325_status_results = "Success." _
AND tx_325_time_status = "Completed OK.")
Then
GOES_Time(1) = reported_year
GOES_Time(2) = reported_month
GOES_Time(3) = reported_day
```

```
GOES_Time(4) = reported_hour
GOES_Time(5) = reported_minute
GOES_Time(6) = reported_second
GOES_Time(7) = reported_tenths_of_a_second * 100000 'tenths to microsec
EndIf
' Ensure the returned time is valid.
If (GOES_Time(4) >= 0 AND GOES_Time(4) < 24 AND GOES_Time(5) >= 0 _
AND GOES_Time(5) < 60 AND GOES_Time(6) >= 0 AND GOES_Time(6) < 60)
Then
' Set the data logger clock to match the GPS time.
ClockSet(GOES_Time(1))
```

Setting the data logger clock to match the GPS time can also be accomplished by adding the status values to the **Numeric Display** in *LoggerNet* and toggling **set_clock_from_GPS** to **True**.

	< rt_tx_data_result_code	-99 longitude_min		reported_latitude_direction_letter	N
Add	st_tx_data_result_code	-99 longitude_direction	87	reported_longitude_direction_letter	W
Fishan	status_result	0 altitude	153942	month_of_last_gps_fix	2
	time_status	0 year_of_last_gps_fix	2023	day_of_last_gps_fix	21
Delete	reported_year	2023 julian_day_of_last_gps_fix	52	month_of_last_missed_gps_atter	1 1
	julian_day	52 hour_of_last_gps_fix	18	day_of_last_missed_gps_attempt	0
Delete All	reported_hour	20 minute_of_last_gps_fix	57	current_tx325_time	2/21/2023 20:37:23:6
Delete All	reported_minute	37 second_of_last_gps_fix	25	current_radio_battery_voltage	13.615
	reported_second	23 number_of_missed_gps_fixes	(current_radio_battery_during_last_	0
Options	reported_tenths_of_a_second	6 year_of_last_missed_gps_fix_attempt	1992	current_battery_voltage_before_la	d 0
	reported_radio_id_decimal	julian_day_of_last_missed_gps_fix_att	C	last_gps_fix_time	2/21/2023 18:57:25
	radio_firmware_build_time	102503 hour_of_last_missed_gps_fix_attempt	C	last_missed_gps_fix_attempt	No misses so far!
stop	radio_firmware_build_date	4232020 minute_of_last_missed_gps_fix_attempt	C	gps_health	Have valid GPS position fix.
	radio_battery_voltage	13615 second_of_last_missed_gps_fix_attempt	(failsafe_status	TX325 is idle.
	radio_temperature	12 radio_gps_health	C	self_timed_transmission_status	t tried to send Self-Timed data yet.
	radio_battery_voltage_before_last_tx	0 radio_failsafe_status	0	random_transmission_status	hot tried to send Random data yet.
	radio_temperature_before_last_tx	0 duration_of_last_radio_transmission	0		
	radio_battery_during_last_tx	0 tx_325_status_results	Success		
	latitude_deg	40 tx_325_time_status	Completed OK		
	latitude_min	reported_month	2		
	latitude_direction	78 reported_day	21		
	longitude_deg	105 reported_radio_id_hex		set_clock_from_GPS	false 🥔

Save this **Numeric Display** configuration by clicking **Numeric Display** > **Options...**> **Setup** > **Save config**. By saving the configuration, users can easily access it at a field site to determine if the TX325 is operating as expected.

NOTE:

Setting the data logger clock is required to determine the Month and Day of the Month. The status array includes the Day of the Year, which must be converted. The conversion will depend on if it is a Leap Year.

The previous code calls the following subroutine:

```
'This subroutine converts day of year (DOY) to months and years
Sub ConvertDayOfYear (_day_of_year As Long, _year As Long, _month As Long, _day As
Long)
Dim leap_year As Boolean
If (_year MOD 4 = 0) Then 'If the year is divisible by 4
leap_year = TRUE
If (_year MOD 100 = 0) AND (_year MOD 400 <> 0) Then
'centuries are not leap years unless they are also divisible by 400
'see https://docs.microsoft.com/en-us/office/troubleshoot/excel/determine-a-leap-year
leap_year = FALSE
```

```
EndIf
Else
 leap_year = FALSE
EndIf
If leap_year = FALSE Then
  'Is the month January
 If _day_of_year <= 31 Then</pre>
   _month = 1 : _day = _day_of_year
  'Is the month February
 ElseIf _day_of_year > 31 AND _day_of_year <= 59 Then</pre>
   _month = 2 : _day = _day_of_year - 31
  'Is the month March
 ElseIf _day_of_year > 59 AND _day_of_year <= 90 Then</pre>
   _month = 3 : _day = _day_of_year - 59
  'Is the month April
 ElseIf _day_of_year > 90 AND _day_of_year <= 120 Then</pre>
   _month = 4 : _day = _day_of_year - 90
  'Is the month May
 ElseIf _day_of_year > 120 AND _day_of_year <= 151 Then</pre>
   _month = 5 : _day = _day_of_year - 120
  'Is the month June
 ElseIf _day_of_year > 151 AND _day_of_year <= 181 Then
   _month = 6 : _day = _day_of_year - 151
  'Is the month July
 ElseIf _day_of_year > 181 AND _day_of_year <= 212 Then</pre>
   _month = 7 : _day = _day_of_year -181
  'Is the month August
 ElseIf _day_of_year > 212 AND _day_of_year <=243 Then</pre>
   _month = 8 : _day = _day_of_year - 212
  'Is the month September
 ElseIf _day_of_year > 243 AND _day_of_year <= 273 Then</pre>
   _month = 9 : _day = _day_of_year - 243
  'Is the month October
 ElseIf _day_of_year > 273 AND _day_of_year <= 304 Then</pre>
   _month = 10 : _day = _day_of_year - 273
  'Is the month November
 ElseIf _day_of_year > 304 AND _day_of_year <= 334 Then</pre>
   month = 11 : _day = _day_of_year - 304
  'Is the month December
 ElseIf _day_of_year > 334 Then
   _month = 12 : _day = _day_of_year - 334
EndIf
ElseIf leap_year = TRUE Then 'Are we in the month of January
  'Is the month January
 If _day_of_year <= 31 Then</pre>
   _month = 1 : _day = _day_of_year
  'Is the month February
 ElseIf _day_of_year > 31 AND _day_of_year <= 60 Then</pre>
   _month = 2 : _day = _day_of_year - 31
```

```
'Is the month March
 ElseIf _day_of_year > 60 AND _day_of_year <= 91 Then</pre>
   _month = 3 : _day = _day_of_year - 60
  'Is the month April
 ElseIf _day_of_year > 91 AND _day_of_year <= 121 Then</pre>
   _month = 4 : _day = _day_of_year - 91
  'Is the month May
 ElseIf _day_of_year > 121 AND _day_of_year <= 152 Then</pre>
   _month = 5 : _day = _day_of_year - 121
  'Is the month June
 ElseIf _day_of_year > 152 AND _day_of_year <= 182 Then</pre>
   _month = 6 : _day = _day_of_year - 152
  'Is the month July
 ElseIf _day_of_year > 182 AND _day_of_year <= 213 Then</pre>
   _month = 7 : _day = _day_of_year -182
  'Is the month August
 ElseIf _day_of_year > 213 AND _day_of_year <=244 Then</pre>
   _month = 8 : _day = _day_of_year - 213
  'Is the month September
 ElseIf _day_of_year > 244 AND _day_of_year <= 274 Then</pre>
   _month = 9 : _day = _day_of_year - 244
  'Is the month October
 ElseIf _day_of_year > 274 AND _day_of_year <= 305 Then</pre>
   _month = 10 : _day = _day_of_year - 274
  'Is the month November
 ElseIf _day_of_year > 305 AND _day_of_year <= 335 Then</pre>
   month = 11 : _day = _day_of_year - 305
  'Is the month December
 ElseIf _day_of_year > 335 Then
   _month = 12 : _day = _day_of_year - 335
 EndIf
EndIf
EndSub
```

Transmitting data

To edit the old program to transmit data, replace the GOESData() CRBasic instruction with the EnviroSatData() instruction. Refer to the *CRBasic Editor* help to determine the changes that need to be made to the parameters.

The GOESData(), GOESGPS(), GOESSetup(), and GOESStatus() CRBasic instructions are not compatible with the TX325. Replace these instructions with the EnviroSat() instructions for the required functionality.

Connection to the data logger RS-232 with LoggerNet

Once a program has been run that sends data to the TX325 through the RS-232 port, the RS-232 port will remain configured at 9600 baud, even after a power cycle. To use the RS-232 interface for *LoggerNet* at its normal baud rate, do the following:

- 1. Connect the SC32B to the data logger CS I/O port.
- 2. Connect to the data logger with the *Device Configuration Utility* software.
- 3. Select the **File Control** tab, select the running program, then click **Stop**. Backup the data logger if desired.
- 4. Select Deployment > Com Ports Settings > ComPort RS-232.
- 5. Set the Baud Rate to 115200 Auto, then click Apply.

```
CAUTION:
Do not run the program again until the RS-232 port is no longer needed.
```

6. Connect to the data logger RS-232 port from the computer running *LoggerNet*.

CAUTION: Do not use the SC32B.

7. Load an OS or other desired task.

After loading and running the program using the RS-232 port to transfer data to a TX325, it will again be set to 9600 baud and will not be able to reliably communicate with *LoggerNet* until the program has stopped from running. When sending a large file like the OS, it will transfer much faster at 115200 rather than 9600 baud.

Appendix G. Compliance documents and certificates

Compliance documents include the ISO certificate (Figure G-1 [p. 80]) and the GOES V2 certificate (Figure G-2 [p. 81]). The TX325 EU Declaration of Conformity is available at: www.campbellsci.com/tx325



Figure G-1. ISO certificate

	Information
	Certificate Number
	12142012
Certifies that	Signal Engineering, Inc.
Model	OmniSat-3
Constantianens Oners	the
	the
Geo-stationary Opera	the tional Environmental Satellite Data Collection System.
Geo-stationary Opera	the tional Environmental Satellite Data Collection System. Condition e that affect its technical performance as specified in the certification standards for this del shall be required before placing in operation.
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Geo-stationary Opera If design changes or modifications are made type of equipment, recertification of this mo In accordance with Version 2.0 GOES DCPR Certi Director, Office of System Development Director, Office of System Development Director, Office of System Development Signature	the tional Environmental Satellite Data Collection System. Condition that affect its technical performance as specified in the certification standards for this del shall be required before placing in operation. fification Standards 300bps and 1200bps data rates. <u>L2 L20 L2</u> Date

Figure G-2. GOES V2 certificate

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Figure G-3. ANATEL certificate of homologation

Limited warranty

Covered equipment is warranted/guaranteed against defects in materials and workmanship under normal use and service for the period listed on your sales invoice or the product order information web page. The covered period begins on the date of shipment unless otherwise specified. For a repair to be covered under warranty, the following criteria must be met:

1. There must be a defect in materials or workmanship that affects form, fit, or function of the device.

2. The defect cannot be the result of misuse.

3. The defect must have occurred within a specified period of time; and

4. The determination must be made by a qualified technician at a Campbell Scientific Service Center/ repair facility.

The following is not covered:

1. Equipment which has been modified or altered in any way without the written permission of Campbell Scientific.

2. Batteries; and

3. Any equipment which has been subjected to misuse, neglect, acts of God or damage in transit.

Campbell Scientific regional offices handle repairs for customers within their territories. Please see the back page of the manual for a list of regional offices or visit www.campbellsci.com/contact to determine which Campbell Scientific office serves your country. For directions on how to return equipment, see Assistance.

Other manufacturer's products, that are resold by Campbell Scientific, are warranted only to the limits extended by the original manufacturer.

CAMPBELL SCIENTIFIC EXPRESSLY DISCLAIMS AND EXCLUDES ANY IMPLIED WARRANTIES OF

MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. Campbell Scientific hereby disclaims, to the fullest extent allowed by applicable law, any and all warranties and conditions with respect to the products, whether express, implied, or statutory, other than those expressly provided herein.

Campbell Scientific will, as a default, return warranted equipment by surface carrier prepaid. However, the method of return shipment is at Campbell Scientific's sole discretion. Campbell Scientific will not reimburse the claimant for costs incurred in removing and/or reinstalling equipment. This warranty and the Company's obligation thereunder is in lieu of all other warranties, expressed or implied, including those of suitability and fitness for a particular purpose. Campbell Scientific is not liable for consequential damage.

In the event of any conflict or inconsistency between the provisions of this Warranty and the provisions of Campbell Scientific's Terms, the provisions of Campbell Scientific's Terms shall prevail. Furthermore, Campbell Scientific's Terms are hereby incorporated by reference into this Warranty. To view Terms and conditions that apply to Campbell Scientific, Logan, UT, USA, see Terms and Conditions 1. To view terms and conditions that apply to Campbell Scientific offices outside of the United States, contact the regional office that serves your country.

Assistance

Products may not be returned without prior authorization. Please inform us before returning equipment and obtain a **return material authorization (RMA) number** whether the repair is under warranty/guarantee or not. See Limited warranty for information on covered equipment.

Campbell Scientific regional offices handle repairs for customers within their territories. Please see the back page of the manual for a list of regional offices or visit

www.campbellsci.com/contact 1 to determine which Campbell Scientific office serves your country.

When returning equipment, a RMA number must be clearly marked on the outside of the package. Please state the faults as clearly as possible. Quotations for repairs can be given on request.

It is the policy of Campbell Scientific to protect the health of its employees and provide a safe working environment. In support of this policy, when equipment is returned to Campbell Scientific, Logan, UT, USA, it is mandatory that a "Declaration of Hazardous Material and Decontamination" form be received before the return can be processed. If the form is not received within 5 working days of product receipt or is incomplete, the product will be returned to the customer at the customer's expense. For details on decontamination standards specific to your country, please reach out to your regional Campbell Scientific office.

NOTE:

All goods that cross trade boundaries may be subject to some form of fee (customs clearance, duties or import tax). Also, some regional offices require a purchase order upfront if a product is out of the warranty period. Please contact your regional Campbell Scientific office for details.

Safety

DANGER — MANY HAZARDS ARE ASSOCIATED WITH INSTALLING, USING, MAINTAINING, AND WORKING ON OR AROUND TRIPODS, TOWERS, AND ANY ATTACHMENTS TO TRIPODS AND TOWERS SUCH AS SENSORS, CROSSARMS, ENCLOSURES, ANTENNAS, ETC. FAILURE TO PROPERLY AND COMPLETELY ASSEMBLE, INSTALL, OPERATE, USE, AND MAINTAIN TRIPODS, TOWERS, AND ATTACHMENTS, AND FAILURE TO HEED WARNINGS, INCREASES THE RISK OF DEATH, ACCIDENT, SERIOUS INJURY, PROPERTY DAMAGE, AND PRODUCT FAILURE. TAKE ALL REASONABLE PRECAUTIONS TO AVOID THESE HAZARDS. CHECK WITH YOUR ORGANIZATION'S SAFETY COORDINATOR (OR POLICY) FOR PROCEDURES AND REQUIRED PROTECTIVE EQUIPMENT PRIOR TO PERFORMING ANY WORK.

Use tripods, towers, and attachments to tripods and towers only for purposes for which they are designed. Do not exceed design limits. Be familiar and comply with all instructions provided in product manuals. Manuals are available at www.campbellsci.com You are responsible for conformance with governing codes and regulations, including safety regulations, and the integrity and location of structures or land to which towers, tripods, and any attachments are attached. Installation sites should be evaluated and approved by a qualified engineer. If questions or concerns arise regarding installation, use, or maintenance of tripods, towers, attachments, or electrical connections, consult with a licensed and qualified engineer or electrician.

General

- Protect from over-voltage.
- Protect electrical equipment from water.
- Protect from electrostatic discharge (ESD).
- Protect from lightning.
- Prior to performing site or installation work, obtain required approvals and permits. Comply with all governing structure-height regulations, such as those of the FAA in the USA.
- Use only qualified personnel for installation, use, and maintenance of tripods and towers, and any attachments to tripods and towers. The use of licensed and qualified contractors is highly recommended.
- Read all applicable instructions carefully and understand procedures thoroughly before beginning work.
- Wear a hardhat and eye protection, and take other appropriate safety precautions while working on or around tripods and towers.
- Do not climb tripods or towers at any time, and prohibit climbing by other persons. Take reasonable precautions to secure tripod and tower sites from trespassers.
- Use only manufacturer recommended parts, materials, and tools.

Utility and Electrical

- You can be killed or sustain serious bodily injury if the tripod, tower, or attachments you are installing, constructing, using, or maintaining, or a tool, stake, or anchor, come in contact with overhead or underground utility lines.
- Maintain a distance of at least one-and-one-half times structure height, 6 meters (20 feet), or the distance required by applicable law, whichever is greater, between overhead utility lines and the structure (tripod, tower, attachments, or tools).
- Prior to performing site or installation work, inform all utility companies and have all underground utilities marked.
- Comply with all electrical codes. Electrical equipment and related grounding devices should be installed by a licensed and qualified electrician.
- Only use power sources approved for use in the country of installation to power Campbell Scientific devices.

Elevated Work and Weather

- Exercise extreme caution when performing elevated work.
- Use appropriate equipment and safety practices.
- During installation and maintenance, keep tower and tripod sites clear of un-trained or non-essential personnel. Take precautions to prevent elevated tools and objects from dropping.
- Do not perform any work in inclement weather, including wind, rain, snow, lightning, etc.

Internal Battery

- Be aware of fire, explosion, and severe-burn hazards.
- Misuse or improper installation of the internal lithium battery can cause severe injury.

• Do not recharge, disassemble, heat above 100 °C (212 °F), solder directly to the cell, incinerate, or expose contents to water. Dispose of spent batteries properly.

Use and disposal of batteries

- Where batteries need to be transported to the installation site, ensure they are packed to prevent the battery terminals shorting which could cause a fire or explosion. Especially in the case of lithium batteries, ensure they are packed and transported in a way that complies with local shipping regulations and the safety requirements of the carriers involved.
- When installing the batteries follow the installation instructions very carefully. This is to avoid risk of damage to the equipment caused by installing the wrong type of battery or reverse connections.
- When disposing of used batteries, it is still important to avoid the risk of shorting. Do not dispose of the batteries in a fire as there is risk of explosion and leakage of harmful chemicals into the environment. Batteries should be disposed of at registered recycling facilities.

Avoiding unnecessary exposure to radio transmitter radiation

• Where the equipment includes a radio transmitter, precautions should be taken to avoid unnecessary exposure to radiation from the antenna. The degree of caution required varies with the power of the transmitter, but as a rule it is best to avoid getting closer to the antenna than 20 cm (8 inches) when the antenna is active. In particular keep your head away from the antenna. For higher power radios (in excess of 1 W ERP) turn the radio off when servicing the system, unless the antenna is installed away from the station, e.g. it is mounted above the system on an arm or pole.

Maintenance

- Periodically (at least yearly) check for wear and damage, including corrosion, stress cracks, frayed cables, loose cable clamps, cable tightness, etc. and take necessary corrective actions.
- Periodically (at least yearly) check electrical ground connections.

WHILE EVERY ATTEMPT IS MADE TO EMBODY THE HIGHEST DEGREE OF SAFETY IN ALL CAMPBELL SCIENTIFIC PRODUCTS, THE CUSTOMER ASSUMES ALL RISK FROM ANY INJURY RESULTING FROM IMPROPER INSTALLATION, USE, OR MAINTENANCE OF TRIPODS, TOWERS, OR ATTACHMENTS TO TRIPODS AND TOWERS SUCH AS SENSORS, CROSSARMS, ENCLOSURES, ANTENNAS, ETC.

Global Sales and Support Network

A worldwide network to help meet your needs



Campbell Scientific Regional Offices

Australia

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